## BOLTZMANN EQUATION AND MOMENT EQUATIONS IN CURVILINEAR COORDINATES

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ABSTRACT: Various forms of writing the Boltzmann equation in an arbitrary orthogonal curvilinear coordinate system are discussed. The derivation is presented of a general transport equation and moment equations containing moments of the distribution function no higher than the fourth. For a gas of Maxwellian molecules it is shown that the system of moment equations for flows which differ little from equilibrium flows transforms into the system of hydrodynamic equations. The resulting equations may be useful in solving problems on motions of a rarefied gas by the moment methods. The results are valid for both the Boltzmann equation and model kinetic equations.

1. All the variations which take place in a rarefied gas in the absence of external forces are described by the Boltzmann equation

$$
\begin{equation*}
\frac{\partial f}{\partial t}+\xi_{x} \frac{\partial f}{\partial x}+\xi_{y} \frac{\partial f}{\partial y}+\xi_{z} \frac{\partial f}{\partial z}=J . \tag{1.1}
\end{equation*}
$$

Here $x, y, z$ are Cartesian coordinates of the physical space; $\xi_{x}$, $\xi_{y}, \xi_{z}$ are components of the molecular velocity vector $\xi$ on the coordinate axes with unit vectors $i, j, k ; f$ is the distribution function, depending on $\mathrm{t}, \mathrm{x}, \mathrm{y}, \mathrm{z}, \xi_{\mathrm{x}}, \xi_{\mathrm{y}}, \xi_{\mathrm{z}} ; \mathrm{J}$ is the collision integral, which is some functional of $f$, whose concrete form is not of interest to us.

We shall transform the Boltzmann equation to an arbitrary orthogonal coordinate system. Let $q_{1}, q_{2}, q_{3}$ be curvilinear coordinates of the point $x, y, z$ of the physical space, so that

$$
x=x\left(q_{1}, q_{2}, q_{3}\right), y=y\left(q_{1}, q_{2}, q_{3}\right), z=z\left(q_{1}, q_{2}, q_{3}\right), \quad \text { (1.2) }
$$

and, conversely,

$$
\begin{equation*}
q_{i}=q_{i}(x, y, z) \quad(i=1,2,3) \tag{1.3}
\end{equation*}
$$

Converting in (1.1) from the Cartesian coordinates $x, y, z$ to the curvilinear coordinates with unchanged $\xi_{\mathrm{X}}, \xi_{\mathrm{y}}, \xi_{\mathrm{z}}$, we obtain

$$
\begin{gather*}
\frac{\partial f}{\partial t}+\frac{\xi_{1}}{H_{1}} \frac{\partial f}{\partial q_{i}}+\frac{\xi_{2}}{H_{2}} \frac{\partial f}{\partial q_{2}}+\frac{\xi_{3}}{H_{3}} \frac{\partial f}{\partial q_{3}}=J, \\
\xi_{i}=\frac{H_{i} \partial q_{i}}{\partial x} \xi_{x}+\frac{H_{i} \partial q_{i}}{\partial u} \xi_{y}+\frac{H_{i} \partial q_{i}}{\partial z} \xi_{x},  \tag{1.4}\\
H_{i}=\sqrt{\left(\partial x / \partial q_{i}\right)^{2}+\left(\partial y / \partial q_{i}\right)^{2}+\left(\partial z / \partial q_{i}\right)^{2}} \quad(i=1 \quad 2,3) . \tag{1.5}
\end{gather*}
$$

Here $\mathrm{H}_{\mathrm{i}}$ are the Lamé parameters.
The quantity $H_{i} \partial q_{i}$ is the length of the arc $\partial s_{i}$ of the coordinate line $q_{i}$, and $H_{i} \partial q_{i} / \partial x$ is the cosine of the angle which the normal to the surface $q_{i}=$ const, and consequently (in view of the system orthogonality) the line $q_{i}$ as well, forms with the $x$-axis. Consequently, $\xi_{i}$ is the projection of the velocity vector $\xi$ on the tangent to the coordinate line $\mathrm{c}_{\mathrm{i}}$. It is obvious that for the same vector $\xi$ the projections $\xi_{i}$ at different points of the physical space are different. Denoting by $e_{1}, e_{2}, e_{3}$ the unit vectors of the curvilinear coordinate system, we write the expression for $\xi_{i}$ in the form

$$
\begin{equation*}
\xi_{i}=\xi_{x}\left(\mathrm{e}_{i} \cdot \mathbf{i}\right)+\xi_{y}\left(\mathrm{e}_{i} \cdot \mathbf{j}\right)+\xi_{x}\left(\mathrm{e}_{i} \cdot \mathbf{k}\right) \quad(i=1,2,3) \tag{1.6}
\end{equation*}
$$

Thus, if the gas motion is considered in the orthogonal curvilinear coordinate system, and the molecular velocities are considered in the Cartesian frame, then for the distribution function $f\left(t, q_{1}, q_{2}, q_{3}, \xi_{X}\right.$, $\xi_{y}, \xi_{z}$ ) we have the Boltzmann equation in the form of (1.4), and $\xi_{i}$ are expressed by Eq. (1.6).

To obtain the transport equations it is advisable to write the Boltzmann equation in divergence form.

To do this, we note that for the fixed vector

$$
\xi=\xi_{x} \mathbf{i}+\xi_{y} \mathfrak{j}+\xi_{z} k=\xi_{1} \mathbf{e}_{1}+\xi_{2} \mathbf{e}_{2}+\xi_{3} \mathrm{e}_{3}
$$

we have the equality

$$
\begin{equation*}
\frac{1}{H_{1} H_{2} H_{3}}\left(\frac{\partial \xi_{1} H_{2} H_{3}}{\partial q_{1}}+\frac{\partial \xi_{2} H_{3} H_{1}}{\partial q_{2}}+\frac{\partial \xi_{3} H_{1} H_{2}}{\partial q_{3}}\right)=0 \tag{1.7}
\end{equation*}
$$

Equation (1.7) may be verified by direct differentiation, if we use the formulas for the derivatives $\partial \xi_{\mathrm{i}} / \partial q_{i}$ which are presented below. However, it is sufficiently obvious physically, since the flux of a constant vector through any closed surface is equal to zero. Considering (1.7), we write the Boltzmann equation in the form

$$
\begin{equation*}
\frac{\partial f}{\partial t}+\frac{1}{H_{1} H_{2} H_{3}}\left(\frac{\partial f \xi_{1} H_{2} H_{3}}{\partial q_{1}}+\frac{\partial f \xi_{2} H_{3} H_{1}}{\partial q_{2}}+\frac{\partial f \xi_{3} H_{1} H_{2}}{\partial q_{3}}\right)=1 \tag{1,8}
\end{equation*}
$$

This equation may also be derived directly, forming, just as in Cartesian coordinates, the balance of the number of particles of velocity $\xi=\xi_{x} i+\xi_{y} j+\xi_{z} k$ for the elemental volume $d \tau=H_{1} H_{2} H_{3} \mathrm{dq}_{1} \mathrm{dq}_{2} \mathrm{dq}_{3}$.

The conversion to curvilinear coordinates may be carried even further. Namely, not only is a point of the physical space specified by the coordinates $q_{1}, q_{2}, q_{3}$, but the molecular velocity is also referred to the curvilinear coordinates, i. e., in place of the arguments $t, q_{1}, q_{2}, q_{3}$, $\xi_{X}, \xi_{y}, \xi_{z}$ in the distribution function we introduce $t, q_{1}, q_{2}, q_{3}, \xi_{1}$; $\xi_{2}, \xi_{3}$. Converting in (1.4) from $\xi_{X}, \xi_{y}, \xi_{Z}$ to $\xi_{1}, \xi_{2}, \xi_{3}$ according to (1.6), and noting that the collision integral is invariant with respect to axis rotation, we obtain

$$
\frac{\partial f}{\partial t}+\xi_{\alpha} \frac{\partial f}{\partial s_{\alpha}}+\xi_{\alpha} \frac{\partial \xi_{\beta}}{\partial s_{\alpha}} \frac{\partial f}{\partial \xi_{\beta}}=J, \quad \frac{\partial}{\partial s_{1}}=\frac{1}{H_{1}} \frac{\partial}{\partial q_{1}}, \quad \text { etc. (1.9) }
$$

The derivatives of $f$ with respect to $q_{i}$ are taken for fixed $\xi_{1}, \xi_{2}$, $\xi_{3}$, and those of $\xi_{B}$ with respect to $q_{\alpha}$ are taken for fixed $\xi_{x}, \xi_{y}, \xi_{z}$. Here and everywhere hereafter the summation is understood over repeating Greek subscripts.

Thus, inertia terms appear in the Boltzmann equation. In order to give (1.9) its final form, we must substitute in place of $\partial \xi_{\beta} / \partial s_{\alpha}$ their expressions in terms of $\xi_{i}, q_{i}$ (see Eqs. (2.4)); however, in view of the complexity this equation will not be written out.
2. To derive the general transport equation we use the Boltzmann equation in the divergence form of (1.8). We note that the transport equation may also be obtained from (1.9).

Let $\varphi\left(\xi_{1}, \xi_{2}, \xi_{3}\right)$ be an arbitrary function of $\xi_{1}, \xi_{2}, \xi_{3}$. Multiplying (1.8) by $\varphi$ and transforming the sum of the derivatives of $f$ to the divergence form, we obtain

$$
\begin{gather*}
\frac{\partial f \varphi}{\partial t}+\frac{1}{H_{1} H_{3} H_{3}}\left(\frac{\partial f \varphi \xi_{1} H_{2} H_{3}}{\partial q_{1}}+\frac{\partial f \varphi \xi_{2} H_{3} H_{1}}{\partial q_{2}}+\frac{\partial f \varphi \xi_{3} H_{1} H_{2}}{\partial q_{3}}\right)-f \Phi=\varphi J,(2.1) \\
\Phi=\frac{\xi_{1}}{H_{1}} \frac{\partial \varphi}{\partial q_{1}}+\frac{\xi_{2}}{H_{2}} \frac{\partial \varphi}{\partial q_{2}}+\frac{\xi_{3}}{H_{3}} \frac{\partial \varphi}{\partial q_{3}} \tag{2.2}
\end{gather*}
$$

The function $\varphi$ depends on the coordinates oniy through the velocity components, so that

$$
\frac{\partial \varphi}{\partial q_{i}}=\frac{\partial \varphi}{\partial \xi_{\alpha}} \frac{\partial \xi_{\alpha}}{\partial q_{i}} \quad(i=1,2,3)
$$

Consequently, $\Phi$ is represented in the form

$$
\begin{equation*}
\Phi=\frac{\partial \varphi}{\partial \xi_{\alpha}}\left(\xi_{\beta} \frac{\partial \xi_{\alpha}}{\partial s_{\beta}}\right) \tag{2.3}
\end{equation*}
$$

The velocity $\xi=\xi_{x} i+\xi_{y} j+\xi_{z} k$ is an independent variable function of the distribution; therefore $\partial \xi / \partial q_{i}=0$, and the derivatives $\partial \xi_{i} / \partial q_{j}$
are nonzero because of the curvilinearity of the coordinate system

$$
\frac{\partial \xi_{i}}{\partial q_{j}}=\frac{\partial\left(\mathbf{e}_{i} \cdot \xi\right)}{\partial q_{j}}=\frac{\partial \mathbf{e}_{i}}{\partial q_{j}} \cdot \xi
$$

Using the formulas for the derivatives of unit vectors with respect to the coordinates $q_{j}$ (see, for example, [1], page 206), we obtain

$$
\begin{gather*}
\frac{\partial \xi_{1}}{H_{1} \partial q_{1}}=-\frac{\xi_{2}}{H_{1} H_{2}} \frac{\partial H_{1}}{\partial q_{2}}-\frac{\tilde{\xi}_{3}}{H_{1} H_{3}} \frac{\partial H_{1}}{\partial q_{3}}, \frac{\partial \xi_{1}}{H_{2} \partial q_{2}}=\frac{\xi_{2}}{H_{2} H_{1}} \frac{\partial H_{2}}{\partial q_{1}} \\
\frac{\partial \xi_{1}}{H_{3} \partial q_{3}}=\frac{\xi_{3}}{H_{1} H_{3}} \frac{\partial H_{3}}{\partial q_{1}} \tag{2.4}
\end{gather*}
$$

and two groups of analogous expressions for the derivatives of $\xi_{2}$ and $\xi_{3}$, which are obtained from (2.4) by cyclic permueation of subscripts.

Substituting into (2.3) the expressions for the derivatives of $\xi_{\alpha}$, according to Eqs. (2.4), we represent $\Phi$ in the form

$$
\begin{equation*}
\Phi=\sum_{i, j=1}^{3}\left(\frac{\xi_{i}{ }^{2}}{H_{i} H_{j}} \frac{\partial H_{i}}{\partial q_{j}}-\frac{\xi_{j} \xi_{i}}{H_{j} H_{i}} \frac{\partial H_{j}}{\partial q_{i}}\right) \frac{\partial \varphi}{\partial \xi_{j}} \tag{2.5}
\end{equation*}
$$

We shall denote by angle brackets the averaged, macroscopic characteristics obtained from microscopic ones by multiplying by the distribution function $f$ and integrating over the entire velocity space. Then, in accordance with (2.1), the general transport equation is written in the form

$$
\begin{gather*}
\frac{\partial\langle\varphi\rangle}{\partial t}+\frac{1}{H_{1} H_{2} H_{3}}\left(\frac{\partial\left\langle\varphi \xi_{1}\right\rangle H_{2} H_{3}}{\partial q_{1}}+\frac{\partial\left\langle\varphi \xi_{2}\right\rangle H_{3} H_{1}}{\partial q_{2}}+\frac{\partial\left\langle\varphi \xi_{3}\right\rangle H_{1} H_{2}}{\partial q_{3}}\right)- \\
-\langle\Phi\rangle=\left\langle J_{\varphi}\right\rangle, \quad\left\langle J_{\varphi}\right\rangle=\int \varphi J d \xi \tag{2.6}
\end{gather*}
$$

3. We shall derive from the general transport equation (2.6) the moment equations, containing moments up to and including the fourth. Following [2], we introduce the notations

$$
\begin{gathered}
u_{i}=\left\langle\xi_{i}\right\rangle ; \quad c_{i}=\xi_{i}-u_{i}, \quad P_{i j}=\left\langle c_{i} c_{j}\right\rangle, \quad p_{i j}=P_{i j}-\delta_{i j} p \\
S_{i j k}=\left\langle c_{i} c_{j} c_{k}\right\rangle, \quad S_{i}=S_{i \alpha \alpha,} \quad Q_{i j h l}=\left\langle c_{i} c_{j} c_{k} c_{l}\right\rangle \\
\left\langle J_{i j}^{(2)}\right\rangle=\int c_{i} c_{j} J d \xi, \quad\left\langle J_{i j h}^{(3)}\right\rangle=\int c_{i} c_{j} c_{k} J d \xi
\end{gathered}
$$

In addition, we denote by $\left\langle\Phi_{i}^{(1)}\right\rangle,\left\langle\Phi_{i j}{ }^{(2)}\right\rangle,\left\langle\Phi_{i j k}^{(3)}\right\rangle$ the averaged values of $\$$ for

$$
\varphi=\xi_{i}, \quad \varphi=\xi_{i} \xi_{j}, \quad \varphi=\xi_{i} \xi_{j} \xi_{k}
$$

Setting $\varphi=1, \varphi=\xi_{i}$ and $\varphi=\xi_{1}{ }^{2}+\xi_{2}{ }^{2}+\xi_{3}{ }^{2}$ in the general transport equation, we obtain the mass, momentum, and energy conservation equations:

$$
\begin{align*}
\frac{\partial \rho}{\partial t}+ & \frac{1}{H_{1} H_{2} H_{3}}\left(\frac{\partial \rho u_{1} H_{2} H_{3}}{\partial q_{1}}+\frac{\partial \rho u_{2} H_{3} H_{1}}{\partial q_{2}}+\frac{\partial \rho u_{8} H_{1} H_{2}}{\partial q_{3}}\right)=0,  \tag{3.1}\\
\frac{\partial \rho u_{i}}{\partial t}+ & \frac{1}{H_{1} H_{2} H_{3}}\left[\frac{\partial}{\partial q_{1}} H_{2} H_{3}\left(\rho u_{1} u_{i}+P_{1 i}\right)+\frac{\partial}{\partial q_{2}} H_{3} H_{1}\left(\rho u_{2} u_{i}+P_{2 i}\right)+\right. \\
& \left.+\frac{\partial}{\partial q_{3}} H_{1} H_{2}\left(\rho u_{3} u_{i}+P_{3 i}\right)\right]-\left\langle\Phi_{i}^{(1)}\right\rangle=0,  \tag{3.2}\\
\frac{\partial\left(3 p+\rho u_{\alpha} u_{\alpha \alpha}\right)}{\partial t} & +\frac{1}{H_{1} H_{2} H_{3}}\left[\frac{\partial}{\partial q_{1}} H_{2} H_{3}\left(\rho u_{1} u_{\alpha} u_{\alpha}+3 u_{1} p+2 u_{\alpha} P_{1 \alpha}+S_{1}\right)+\right. \\
& +\frac{\partial}{\partial q_{2}} H_{3} H_{1}\left(\rho u_{2} u_{\alpha} u_{\alpha}+3 u_{2} p+2 u_{\alpha} P_{2 \alpha}+S_{2}\right)+ \\
& \left.+\frac{\partial}{\partial q_{3}} H_{1} H_{2}\left(\rho u_{3} u_{\alpha} u_{\alpha}+3 u_{3} p+2 u_{\alpha} P_{3 \alpha}+S_{3}\right)\right]=0 \tag{3.3}
\end{align*}
$$

The expressions for $\left\langle\Phi_{i}{ }^{(0)}\right\rangle$ are easily obtained from (2.5):

$$
\left\langle\Phi_{i}^{(1)}\right\rangle=-\left(\rho u_{1} u_{2}+P_{12}\right) \frac{1}{H_{1} H_{2}}-\frac{\partial H_{1}}{\partial q_{2}}-\left(\rho u_{1} u_{3}+P_{13}\right) \frac{1}{H_{1} H_{3}} \frac{\partial H_{1}}{\partial q_{3}}+
$$

$$
\begin{equation*}
+\left(\rho u_{2}^{2}+P_{22}\right) \frac{1}{H_{2} H_{1}} \frac{\partial H_{2}}{\partial q_{1}}+\left(\rho u_{3}^{2}+P_{33}\right) \frac{1}{H_{3} H_{1}} \frac{\partial H_{3}}{\partial q_{1}}, \tag{3.4}
\end{equation*}
$$

as are the analogous expressions for $\left\langle\Phi_{2}{ }^{(1)}\right\rangle$ and $\left\langle\Phi_{3}{ }^{(1)}\right\rangle$. Using the equation of continuity and the momentum equation, we write the energy in the form

$$
\begin{aligned}
& \frac{\partial p}{\partial t}+\frac{1}{H_{1} H_{2} H_{3}}\left[\frac{\partial}{\partial q_{1}} H_{2} H_{3}\left(u_{1} p+\frac{1}{3} S_{1}\right)+\frac{\partial}{\partial q_{2}} H_{3} H_{1}\left(u_{2} p+\frac{1}{3} S_{2}\right)+\right. \\
& \left.+\frac{\partial}{\partial q_{3}} H_{1} H_{2}\left(u_{3} p+\frac{1}{3} S_{3}\right)\right]+\frac{2}{3} P_{\alpha \beta} \frac{\partial u_{\alpha}}{\partial s_{\beta}}+\frac{2}{3} u_{\alpha}\left\langle\Phi_{2}^{(1)}\right\rangle=0 .
\end{aligned}
$$

Now we set $\varphi=\xi_{i} \xi_{j}$ and $\varphi=\xi_{i} \xi_{j} \xi_{\mathrm{k}}$ in (2.6). Performing the same transformations as in the derivation of the corresponding equations in Cartesian coordinates [2], we obtain

$$
\begin{align*}
& \frac{\partial P_{i j}}{\partial t}+\frac{1}{H_{1} H_{2} H_{3}}\left[\frac{\partial}{\partial q_{1}} H_{2} H_{S}\left(u_{1} P_{i j}+S_{i j 1}\right)+\frac{\partial}{\partial q_{2}} H_{3} H_{1}\left(u_{2} P_{i j}+S_{i j 2}\right)+\right. \\
& \left.+\frac{\partial}{\partial q_{3}} H_{1} H_{2}\left(u_{3} P_{i j}+S_{i j 3}\right)\right]+P_{j \alpha_{i}} \frac{\partial u_{i}}{\partial s_{\alpha}}+P_{\alpha i} \frac{\partial u_{j}}{\partial s_{\alpha}}- \\
& -\left\langle\Phi_{i j}^{(2)}\right\rangle+u_{\hat{p}}\left\langle\Phi_{i^{(1)}}\right\rangle+u_{i}\left\langle\Phi_{j}^{(1)}\right\rangle=\bar{I}_{i j}{ }^{(2)}  \tag{3.6}\\
& \frac{\partial S_{i j k}}{\partial t}+\frac{1}{H_{1} H_{2} H_{3}}\left[\frac{\partial}{\partial q_{1}} H_{2} H_{3}\left(u_{i} S_{i j k}+Q_{i j h 1}\right)+\frac{\partial}{\partial q_{2}} \not H_{3} H_{1}\left(u_{2} S_{i j k}+Q_{i j k 2}\right)+\right. \\
& \left.+\frac{\partial}{\partial q_{3}} H_{1} H_{2}\left(u_{3} S_{i j k}+Q_{i j k 3}\right)\right]+S_{i j \alpha} \frac{\partial u_{k}}{\partial s_{\alpha}}+S_{i \alpha k} \frac{\partial u_{j}}{\partial s_{\alpha \alpha}}+S_{\alpha j k} \frac{\partial u_{i}}{\partial s_{\alpha}}- \\
& -\frac{1}{\rho H_{1} H_{2} H_{3}}\left(P_{i j} \frac{\partial H_{2} H_{3} P_{1 k}}{\partial q_{1}}+P_{j k} \frac{\partial H_{2} H_{3} P_{1 i}}{\partial q_{i}}+P_{k i} \frac{\partial H_{2} H_{3} P_{1 j}}{\partial q_{1}}+\right. \\
& +\mathrm{P}_{i j} \frac{\partial H_{3} H_{1} P_{2 k}}{\partial q_{2}}+P_{j k} \frac{\partial H_{3} H_{1} P_{2 i}}{\partial q_{2}}+P_{k i} \frac{\partial H_{3} H_{1} p_{2 j}}{\partial q_{2}}+ \\
& \left.+P_{i} \frac{\partial H_{1} H_{2} P_{3 k}}{\partial q_{3}}+P_{j k} \frac{\partial H_{1} H_{2} P_{3 i}}{\partial q_{3}}+P_{k i} \frac{\partial H_{1} H H_{2} P_{3 i}}{\partial q_{3}}\right)+ \\
& +\frac{1}{\rho}\left\langle P_{i j}\left\langle\Phi_{k^{(1)}}\right\rangle+p_{j k}\left\langle\Phi_{i^{(1)}}\right\rangle+p_{i k i}\left\langle\Phi_{j}^{(1)}\right\rangle\right)-\left\langle\Phi_{i j k}\right\rangle+ \\
& +u_{k}\left\langle\Phi_{i j}{ }^{(2)}\right\rangle+u_{i}\left\langle\Phi_{j k}^{(2)}\right\rangle+u_{j}\left\langle\left\langle\Phi_{k i}^{(2)}\right\rangle-u_{i} u_{j}\left\langle\Phi_{k}{ }^{(1)}\right\rangle-u t_{j} u_{k}\left\langle\Phi_{i}^{(1)}\right\rangle-\right. \\
& -u_{k} u_{i}\left\langle\Phi_{j}^{(1)}\right\rangle=\left\langle I_{i j k}^{(3)}\right\rangle . \tag{3.7}
\end{align*}
$$

The quantities $\left\langle\Phi_{i j h}^{(3)}\right\rangle,\left\langle\Phi_{i j}^{(2)}\right\rangle$, are calculated elementarily on the basis of (2.5): however, because of length they are not presented here.
4. Equations (3.6), (3.7) in the case of Maxwellian molecules make it possible to obtain expressions for the stresses and the thermal fluxes in the hydrodynamic approximation. Converting from $\mathrm{P}_{\mathrm{ij}}$ to $\mathrm{p}_{\mathrm{ij}}$ and excluding $\partial \mathrm{p} / \partial t$ with the aid of the energy equation in the form (3.5), we write (3.6) in the form

$$
\begin{aligned}
\frac{\partial p_{i j}}{\partial t}+ & \frac{1}{H_{1} H_{2} H_{3}}\left[\frac{\partial}{l \partial q_{1}} H_{2} H_{3}\left(u_{1} p_{i j}+S_{i j 1}-\frac{1}{3} \delta_{i j} S_{1}\right)+\right. \\
& +\frac{\partial}{\partial q_{2}} H_{3} H_{1}\left(u_{2} p_{i j}+S_{i j 2}-\frac{1}{3} \delta_{i j} S_{2}\right)+ \\
+ & \left.\frac{\partial}{\partial q_{3}} H_{4} H_{2}\left(u_{3} p_{i j}+S_{i j 3}-\frac{1}{3} \delta_{i j} S_{3}\right)\right]+ \\
& +p_{j \alpha} \frac{\partial u_{i}}{\partial s_{\alpha}}+p_{\alpha i} \frac{\partial u_{j}}{\partial s_{\alpha}}-\frac{2}{3} \delta_{i j} p_{\alpha \beta} \frac{\partial u_{\alpha}}{\partial s_{\beta}}+ \\
& +p\left(\frac{\partial u_{i}}{\partial s_{i}}+\frac{\partial u_{j}}{\partial s_{i}}-\frac{2}{3} \delta_{i j} \frac{\partial u_{\alpha}}{\partial s_{\alpha}}\right)- \\
-\left\langle\Phi_{i j}^{(2)}\right\rangle & +u_{j}\left\langle\Phi_{i}^{(1)}\right\rangle+u_{i}\left\langle\Phi_{j}^{(1)}\right\rangle-\frac{2}{3} \delta_{i j^{i l \alpha}}\left\langle\Phi_{\alpha}^{(1)}\right\rangle=\left\langle I_{i j}^{(2)}\right\rangle \text {. (4. 1) }
\end{aligned}
$$

For Maxwell molecules

$$
\left\langle I_{i j}^{(2)}\right\rangle=-p \mu^{-1} p_{i j}
$$

Passing in (4.1) to the limit as $\mu \rightarrow 0$ and combining terms in $\delta_{i j}$, we find the expression for $p_{i j}$ :

$$
\begin{gather*}
p_{i j}=-\mu\left[\frac{H_{i}}{H_{j}} \frac{\partial}{\partial q_{j}}\left(\frac{u_{i}}{H_{i}}\right)+\frac{H_{j}}{H_{i}} \frac{\partial}{\partial q_{i}}\left(\frac{u_{i}}{H_{j}}\right)\right](i \neq j),  \tag{4.2}\\
p_{i i}=-\mu\left\{2\left[\frac{u_{a}}{H_{i}} \frac{\partial H_{i}}{\partial s_{\alpha}}+\frac{\partial}{\partial q_{i}}\left(\frac{u_{i}}{H_{i}}\right)\right]-\right. \\
\left.-\frac{2}{3} \frac{1}{H_{:} H_{2} H_{3}}\left(\frac{\partial u_{1} H_{2} H_{3}}{\partial q_{i}}+\frac{\partial u_{2} H_{3} H_{1}}{\partial q_{2}}+\frac{\partial u_{3} H_{1} H_{2}}{\partial q_{3}}\right)\right\}, \tag{4.3}
\end{gather*}
$$

Considering that the deformation rate tensor components are expressed by the equations [3]

$$
\begin{gather*}
2 \varepsilon_{i j}=\frac{H_{i}}{H_{j}} \frac{\partial}{\partial g_{j}}\left(\frac{u_{i}}{H_{i}}\right)+\frac{H_{j}}{H_{i} \cdot \partial q_{i}}\left(\frac{\partial}{H_{j}}\right) \quad(i \neq j),  \tag{4.4}\\
\varepsilon_{i i}=\frac{u_{\alpha}}{H_{i}} \frac{\partial H_{i}}{\partial s_{\alpha}}+\frac{\partial}{\partial q_{i}}\left(\frac{u_{i}}{H_{i}}\right), \tag{4.5}
\end{gather*}
$$

we obtain the linear connection between the stress tensor and the deformation rate tensor which is usual for Navier-Stokes theory:

$$
\begin{equation*}
p_{i j}=-2 \mu \varepsilon_{i j}, \quad p_{i i}=-2 \mu \varepsilon_{i i}+2 / 3 \mu \varepsilon_{i a} \quad(i \neq j) \tag{4.6}
\end{equation*}
$$

We obtain the expression for the thermal flux components $S_{i} / 2$ from (3. 7). For Maxwellian molecules

$$
\left\langle I_{i j k}^{(3)}\right\rangle=\frac{p}{6_{j}}\left(S_{i} \delta_{i k}+S_{j} \delta_{i k}+S_{k} \delta_{i j}-9 S_{i j k}\right) .
$$

We set $j=k=\alpha$ in (2.8), sum with respect to $\alpha$, and pass to the limit as $\mu \rightarrow 0$. Noting that in the limit

$$
Q_{i j k l}=p R T\left(\delta_{i j} \delta_{k l}+\delta_{i k} \delta_{j t}+\delta_{i l} \delta_{j k}\right)
$$

and that all the terms depending on $\Phi$ cancel one another, we arrive at the usual expression of the Eourier law for a monatomic gas.

$$
\begin{equation*}
5 / 2 S_{i}=-\lambda \frac{\partial T}{H_{i} \partial q_{i}} \quad(\lambda=15 / 4 R \mu) \tag{4.7}
\end{equation*}
$$

5. The transport equations and the moment equations presented above, written in universal form, may be useful for solving problems by the moment method, i. e., by the method of closing the system of moment equations by suitable approximation of the distribution function. In particular, we could write the 13 -moment Grad equation, specifying, just as in [2], the form of the distribution function. However, this approach is not justified because of the asymptotic nature of the series convergence.

In conclusion we note that the form of the collisional term was not used in the arguments presented above, other than $\S 4$, so that the results are valid for both the Boltzmann equation and its kinetic models.

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