

Advanced Multirotor Drone
Meeting Minutes 4/12/2019

Members present:

- Preston Stephens
- Pengqiang Ge
- Matthew Shryock
- Caleb Smith
- Makynzie Zimmer

Major Actions:

- Run the four motors in the 360 degree test bend using simple remote controller
- Run the two motors in the Teeter-Totter using customized PCB dual motor
- Run the two motors in the Teeter-Totter
- Calibrated ESC with simple remote control
- Double check state machine functions
- assembled the small balloon

Next Steps:

- Run the two motors in the Teeter-Totter using ESC test bend
- Display different gestures of drone using remote control