Anti-Theft Shocking Door Handle

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Design Objectives

- Theft deterrence via electrical shock
- 4 Hz switching
- Remote power ON/OFF
- Testing and measuring outputs

Design 1 Overview



- Jacob's ladder
 - Generates electrical arcs from bottom up.
- Uses extremely high voltages
 - The busses would need to be mounted to hinges

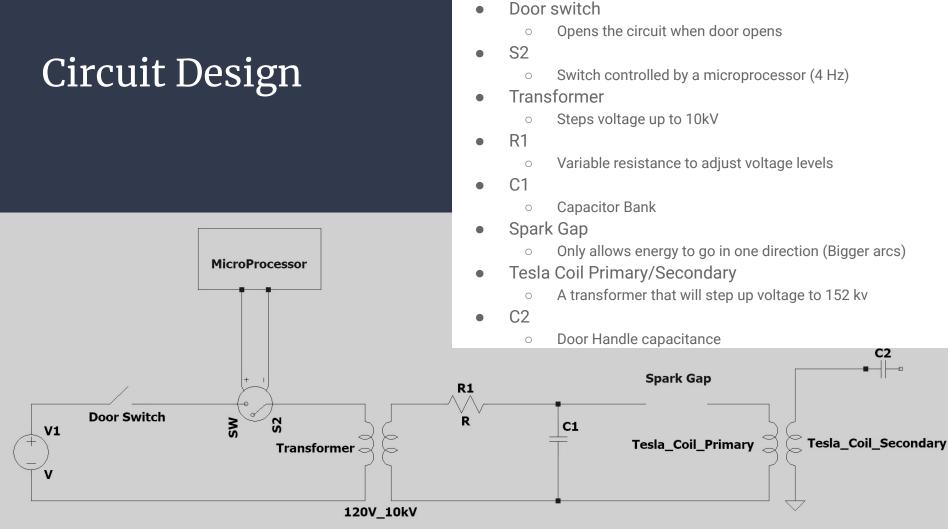
Design 2 Overview



- Tesla coil used to generate voltage for arcing
 - Mounted inside NEMA electrical box
- Customized Door Handle for directing arc direction.
 - Only the outside handle will produce an arc
- Microprocessor and Infrared sensors
 - For motion sensing and switching control

Design Decision Matrix

Engineering Decision Matrix						
Criteria	Weight	Design 1	Design 2			
Simplicity	0.15	5	6			
Cost	0.25	7	7			
Safety	0.5	2	8			
Ease of use	0.1	5	10			
Overall rating	1	0.4	0.765			



Heat Sink





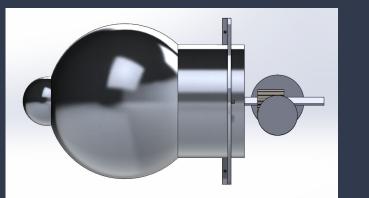
- To be mounted on the capacitor bank.
 - Amount of heat dissipation needed to be determined.
- Dependant on the capacitance C1.
 - Capacitance of the primary capacitor

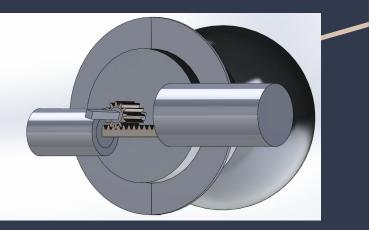
Handle Design



- Designed to produce an arc from the tip
 - Aluminum 6061
- Rose Cover
 - Non-conductive material (3D printed plastic)
 - Fastened with non-conductive screws.

Door/Handle Design 1





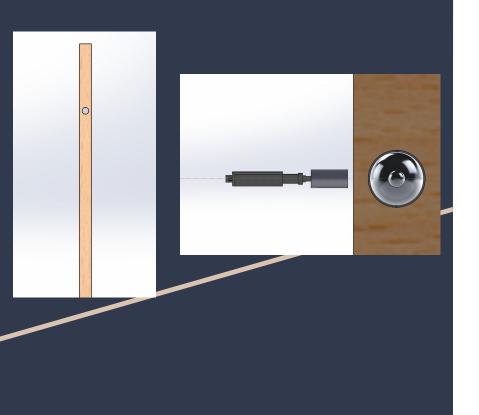
- Rack and pinion design
 - Gear Stock and Metal Rack
- Retract the Deadbolt linearly by an applied moment on the handle.
- Key to be interfaced with moldable rubber.

Door/Handle Design 2



• Use existing door latch assembly to interface with door handle.

Door/Handle Design 3

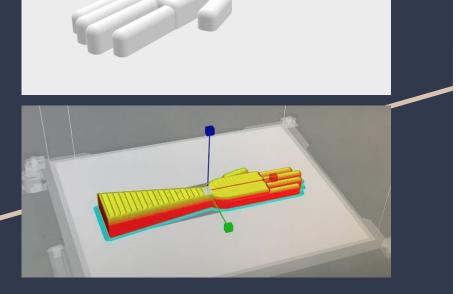


- Linear actuator to dead bolt
- Magnets to act as way to hold the door in place when not armed.

Door/Handle Decision Matrix

Engineering Decision Matrix					
Criteria	Weight	Design 1	Design 2	Design 3	
Simplicity	0.15	3	5.5	9	
Cost	0.15	3	10	6	
Odds of Succes	0.3	3	5	8	
Ease of Use	0.4	5	7	9	
Overall rating	1	0.38	0.6625	0.825	

Testing



- 3D Print hand out of 3mm High Impact Polystyrene (HIPS)
- Material melting point = 240 degrees celsius
- Dimensions: X axis = 216.4386mm. Y axis = 70.1793mm. Z axis = 22.5mm.
- Silicone spray to replicate human skin

Budget

• Budget \$1000.00

Expense Items	Predicted Cost	Actual Cost
Sensor(s)	\$10.00	
Wire(s)	\$30.00	
Microprocessor	\$50.00	
Magnet Wire	\$35.00	
Power supply components	\$50.00	
ME misc supplies	\$75.00	
Motor	\$15.00	
Robotic Arm	\$20.00	
Misc EE components	\$10.00	
Plastic Tubing	\$12.00	
Metal Bar	\$125.00	
Door and frame	\$100.00	\$50.00
Insulation	\$60.00	
Led lights	\$20.00	
Insulated gloves	\$100.00	
Safety equipment	\$100.00	
Total:	\$812.00	\$50.00

Questions?

