

engineering 🔺 design



Data Acquisition System for Synchronous Generator Transient Performance

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 Project Goal Specifications Project Topology Project Learning & Results Project Budget



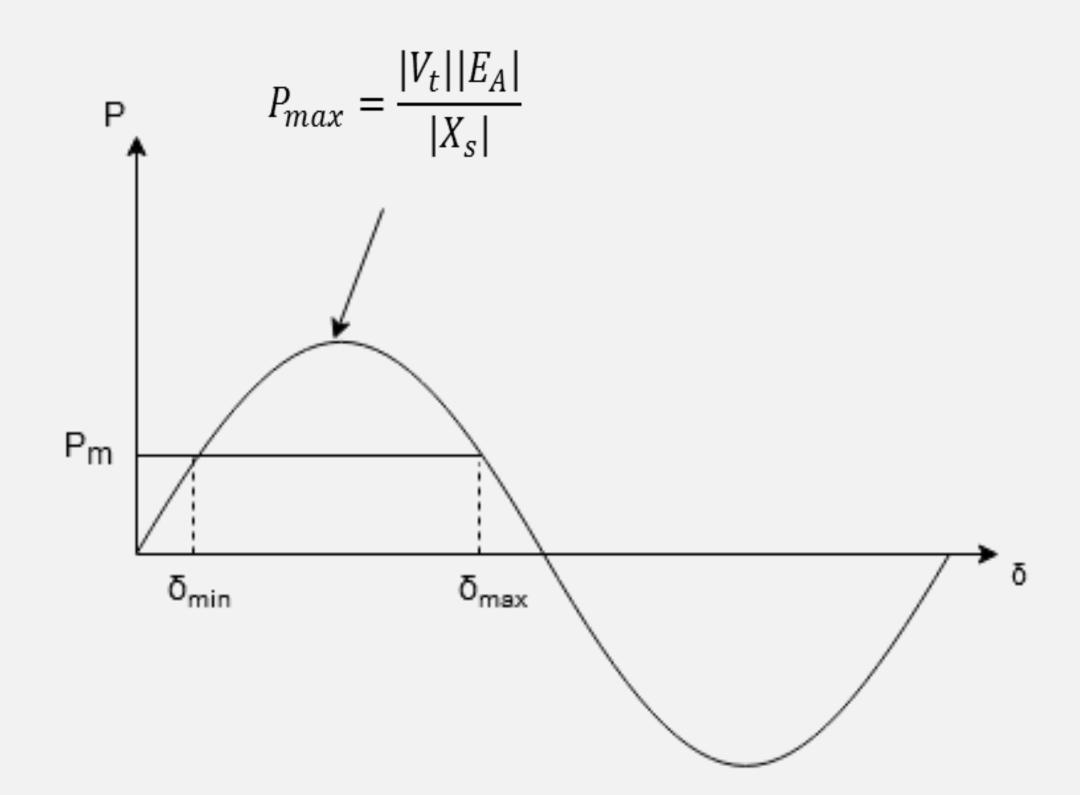


Problem Statement

After a fault occurs

The angle of the generator will increase and may exceed δ_{max}
The generator may slip a pole.







Project Goal

Design and implement a system to acquire measurements from a synchronous generator in transient conditions.









Specification

Measurement Requirements

- Terminal voltage and current
- Field voltage and current
- Torque and power
- Speed and frequency
- Load phase angle

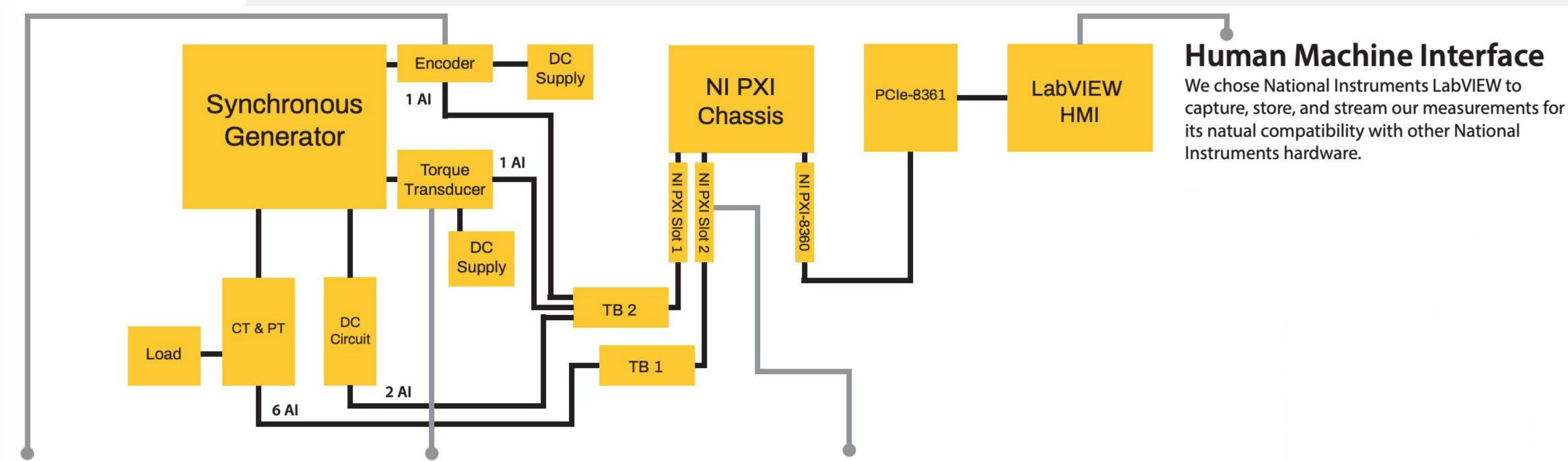


Device Requirements

- Sampling rate of at least 10 kHz
- Measurements must be time synchronized
- Monitoring and storage of streamed measurements



System Topology



Encoder

Torque Transducer

An encoder is required to measure speed and the Z The Himmelstein MCRT 48202V(1-3) Torque pulse signal. The encoder we used is the BEI Sensors H25 Incremental Optical Encoder. The Z pulse is used in tandem with the zero crossing of a terminal voltage to calculate the load phase angle.

Transducer outputs an analog voltage proportional to the current torque on the shaft. The average torque can be calculated from the peak torque in the induced harmonic.



Data Acquisition Board

The National Instruments PXI 6251 Data Acquisition Board captures and digitizes analog signals. The PXI chassis then sends the signals to the computer through a PCI connection.





Data Acquisition Board







National Instruments PXI 6289 & 6251



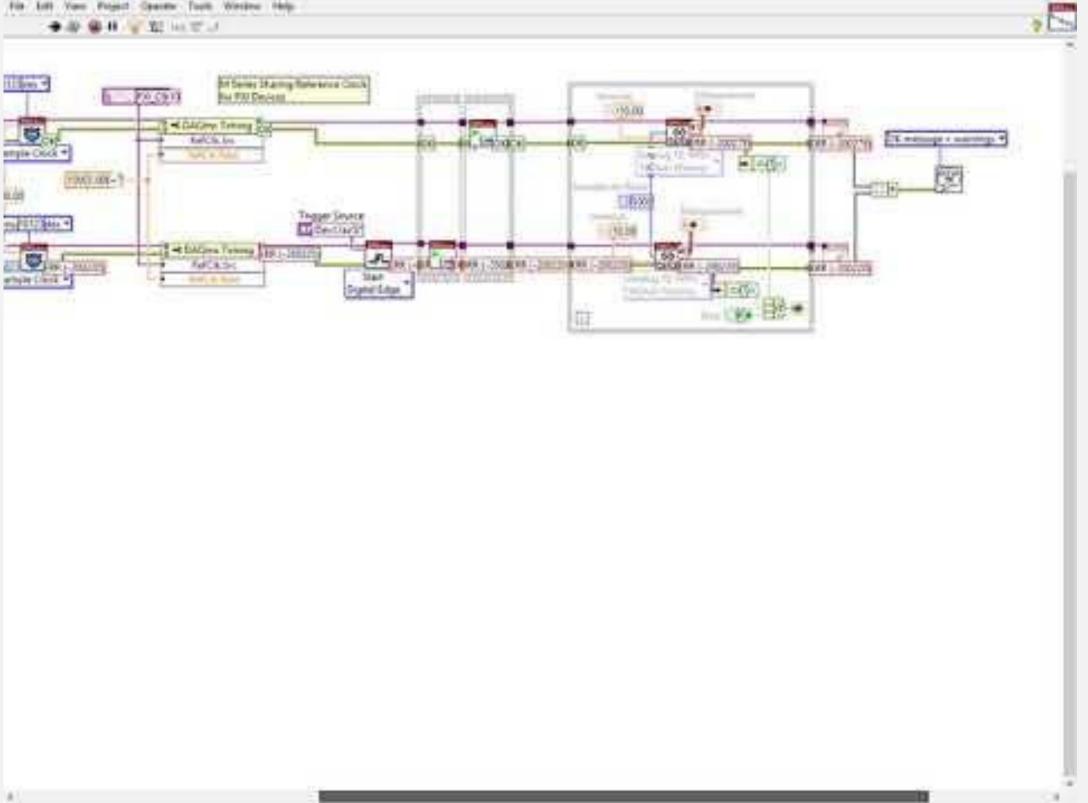


	PXI 6289	PXI 6251
Number of Channels	16 AI	8 AI
ADC resolution	18 Bits	16 Bits
Sample rate	500 kS/s	1 MS/s



Synchronizing 2 DAQs

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AC & DC Measurement





Shunt Resistor **Generator Rating Generator Rating** DAQ Acceptable for Current Signal Current Voltage Measurement 1 Ohm 220 V 35.4 A $\pm 11V$ 50 W





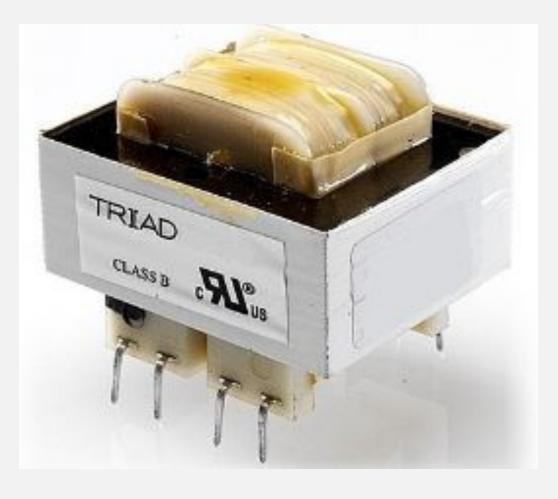
Potential Transformer

Model	Rating	Spec Ra
FS24-500	230V:12V	19.2



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2:1





Current Transformer

Model	Rating	Ra
114-151	150A:5A	30





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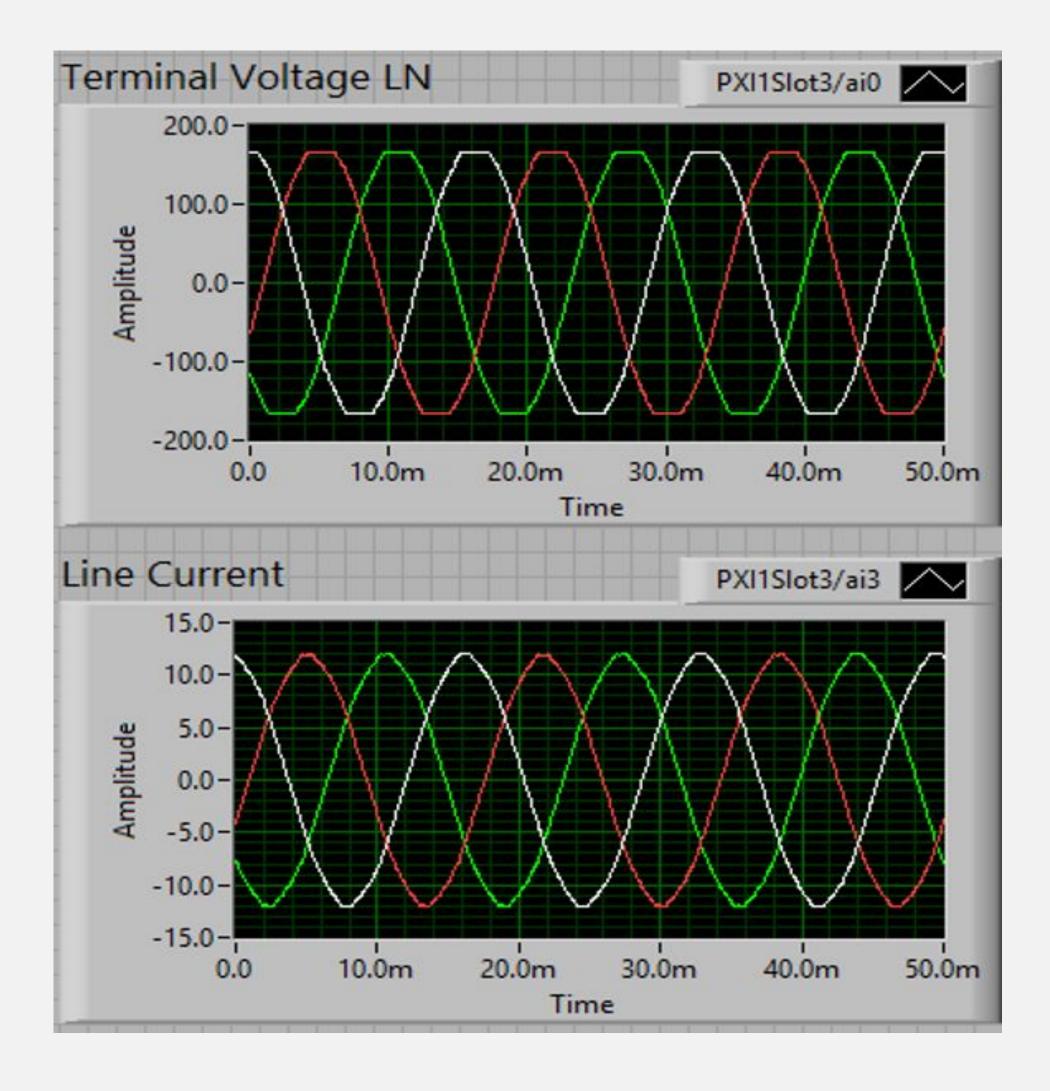
Line to Neutral Voltage and Line **Current from LabVIEW**

Rating L-N Voltage	Load	Calcula ⁻ Cur
127 V RMS 179.6V Peak	14.8Ω	8.58A 12.14



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A RMS A Peak

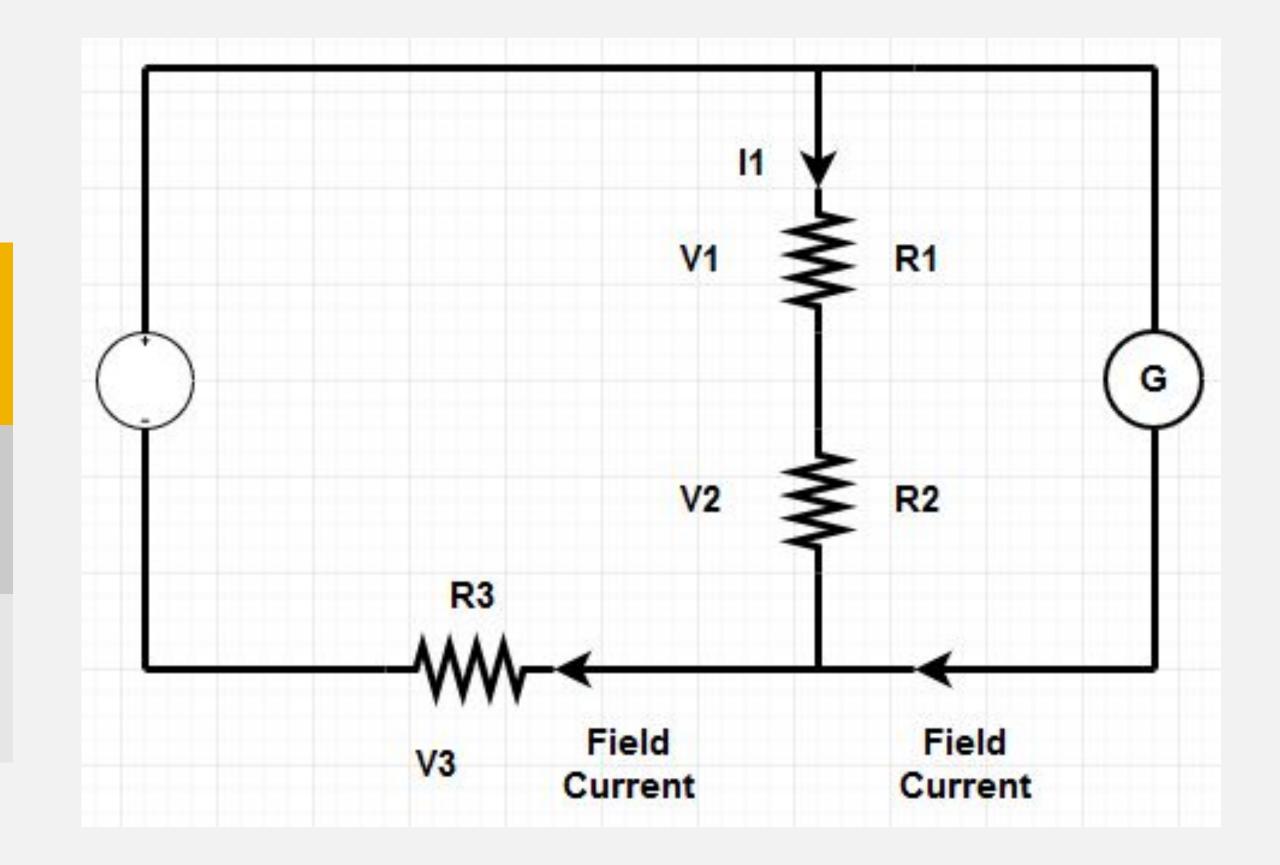




Circuit for DC Measurement

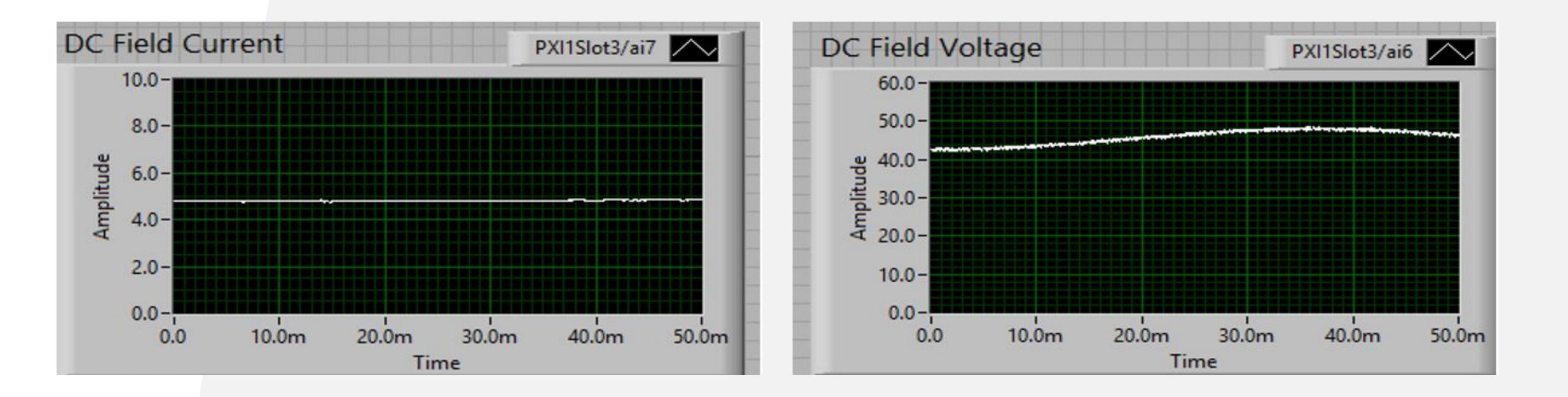
Shunt Resistor	R1	R2	R3
Resistance	20kΩ	1kΩ	0.10
Power Rating	10 W	10 W	50W







Field Current and Field Voltage from LabVIEW









Torque Transducer



Torque Transducer Himmelstein MCRT 408202V

Inputs:

- 2-Pin DC Power Supply
- 3-Pin RS232 Digital Communication
- 4-Pin Analog Communication





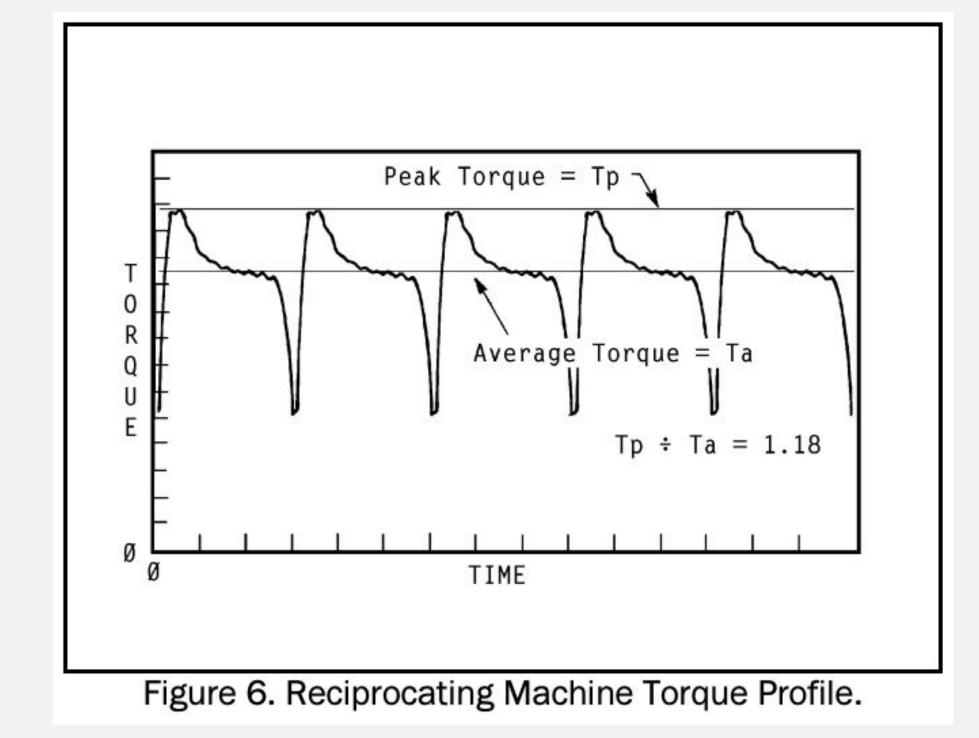


Analog Output

Superimposed Harmonics

Tavg = Tpeak/1.18





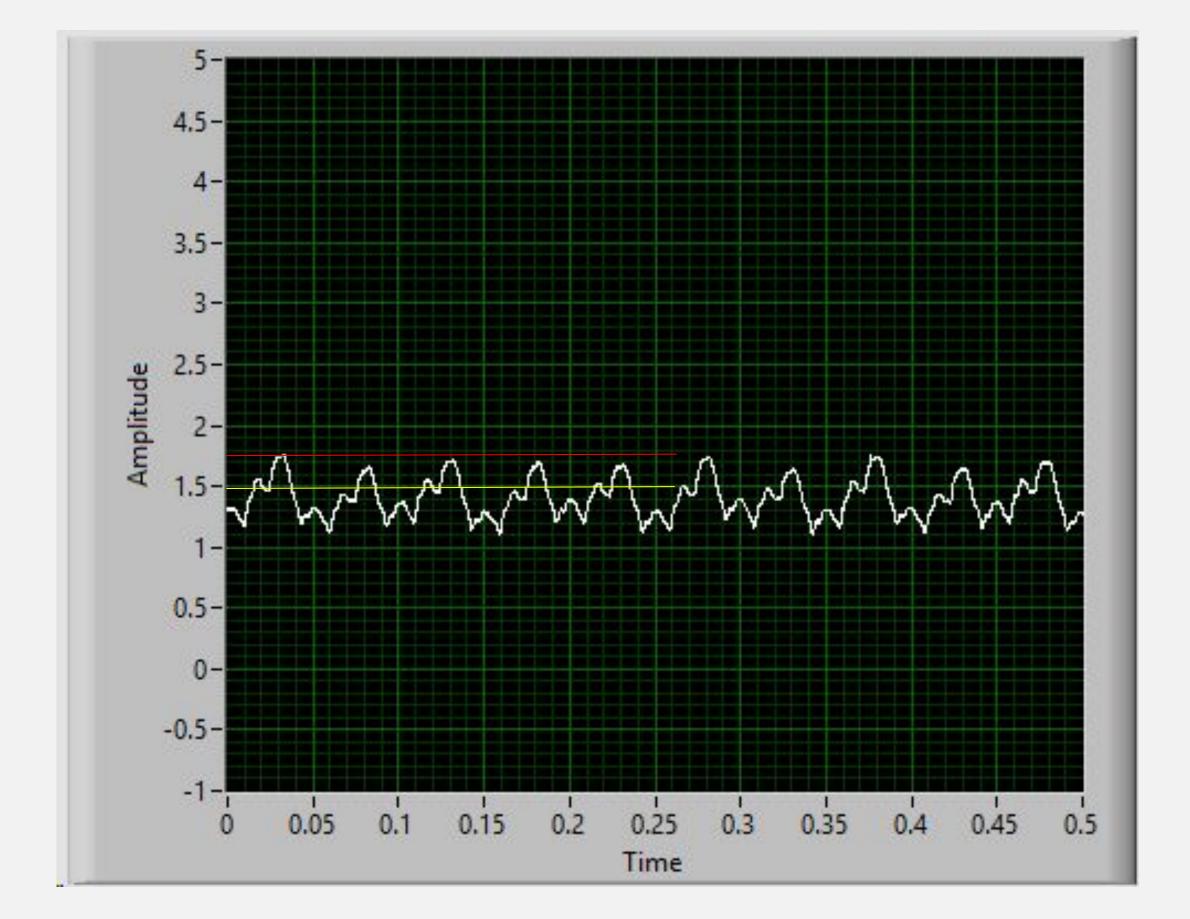


Analog Output

Example

Peak ≈ 1.7 Avg ≈ 1.5 Peak/Avg = 1.13 ≈ 1.18

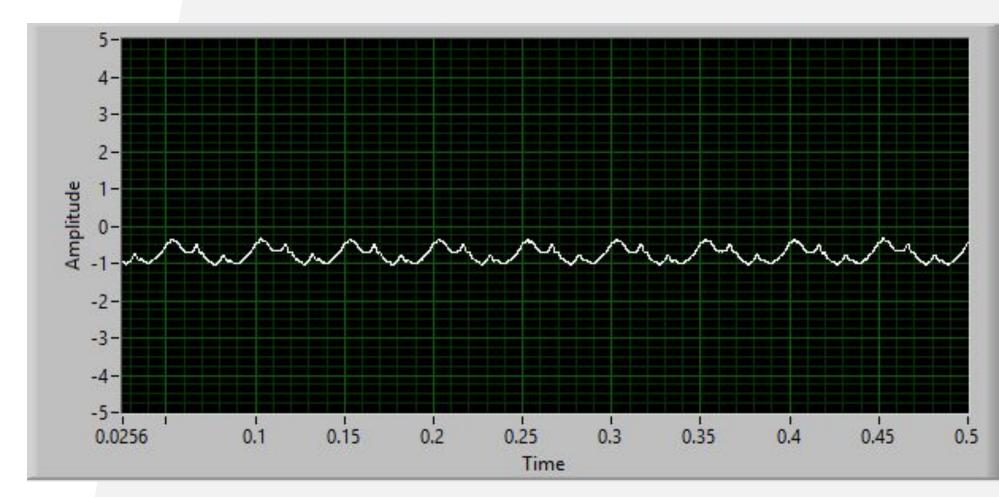






Analog Output **Mapping Example**

Analog from LabVIEW

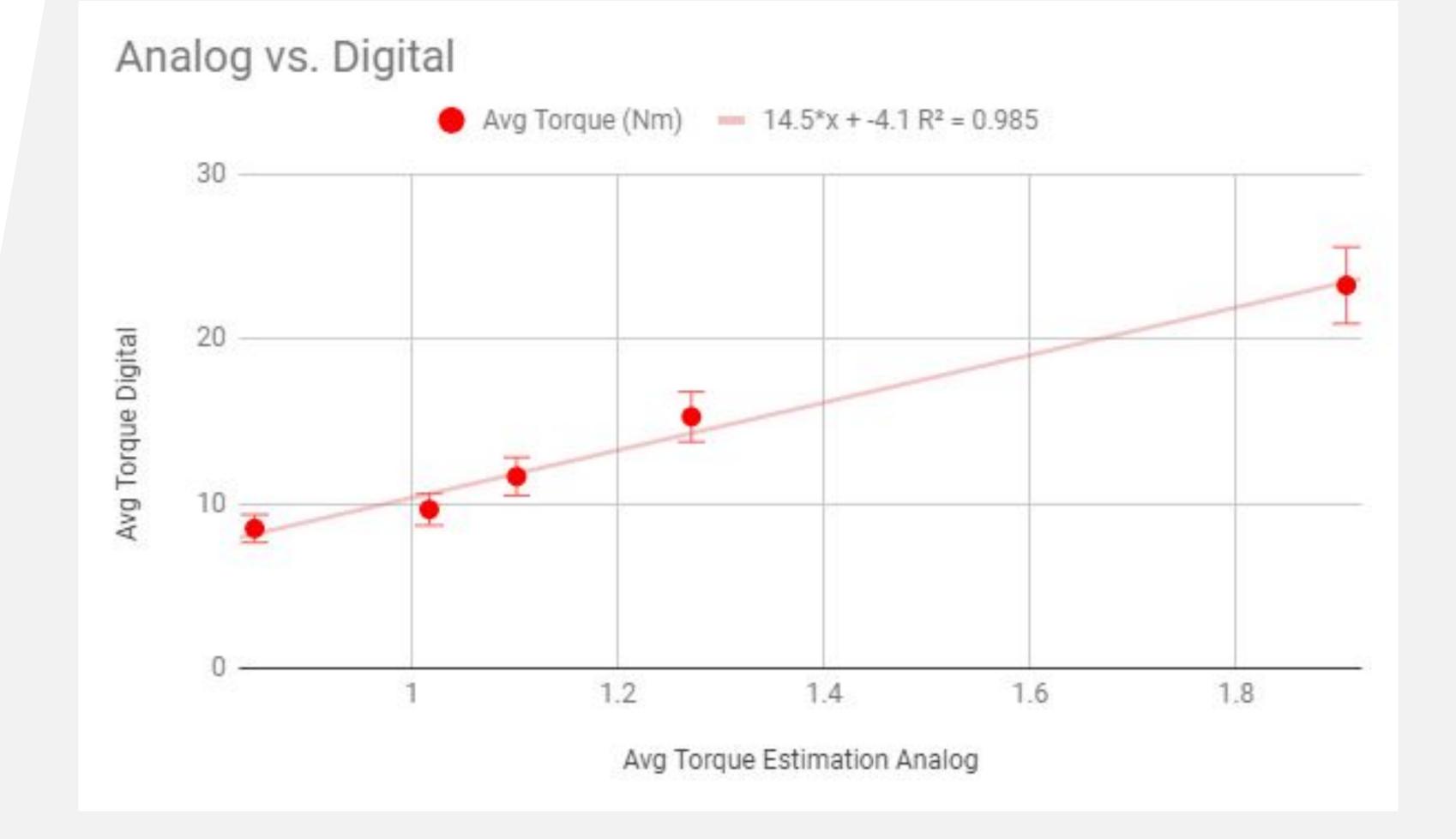


Digital from DT482

– Ø X LCT-COM3 v3.256.0 Firmware: 3.028 MCRT48202V(1-3)-533.VA009852-COM Units Filter:200 Ha 116.64 - -121.37 = 238.01 -6.99 N-m Tare:0.00 +CAL:112.98 Clear Tare 🗖 Dots 🥅 Stop Graphing -CAL:-112.98 Save Data 2/27/2019 10:14:45 PM 18 Samples/sec 10 sec per screen



Analog Digital Torque Relation











Encoder



Encoder

Type: BEI Sensors H25 Incremental Optical Encoder

• Has three signals: A, B, & Z

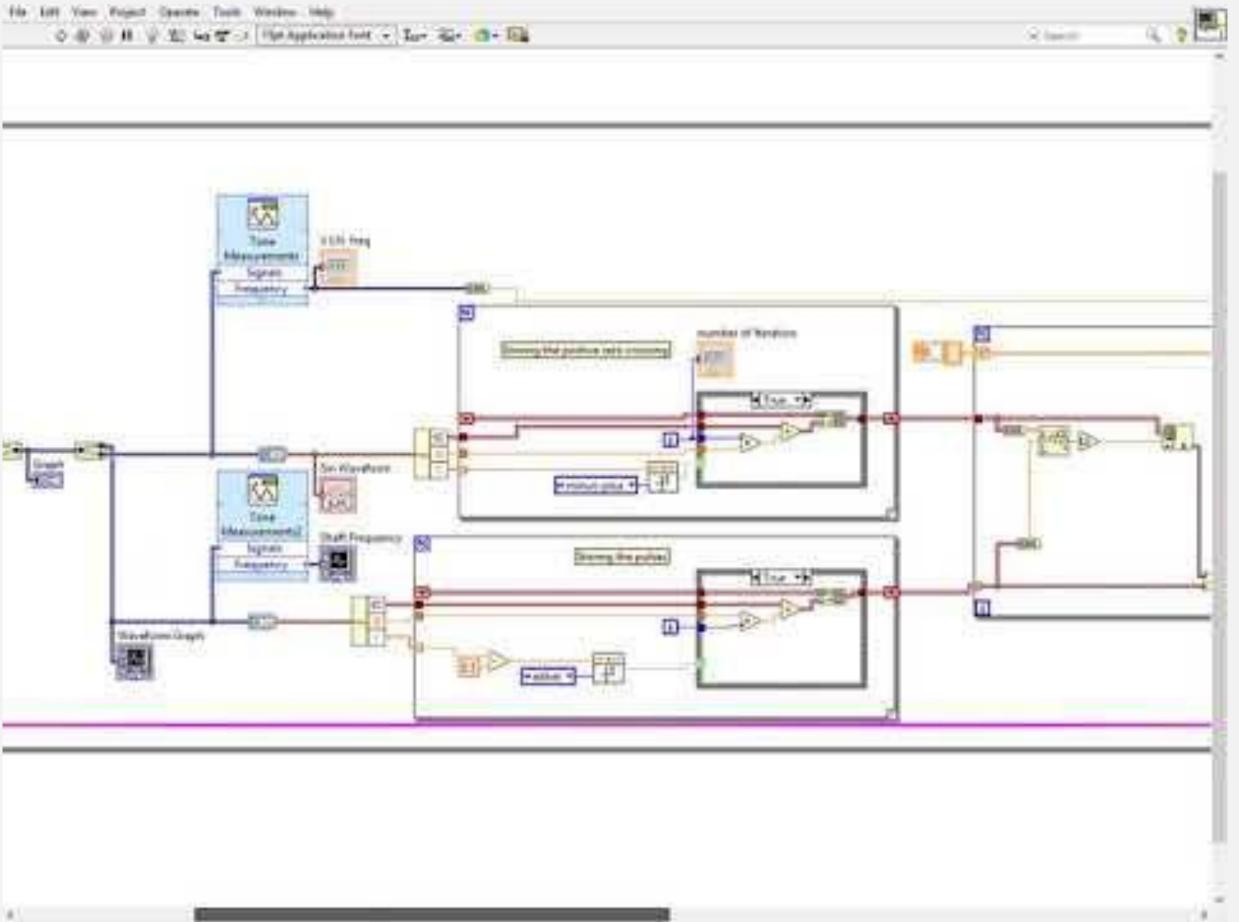






Load Angle

His last Your Fright Causes Tools Wesley, Help

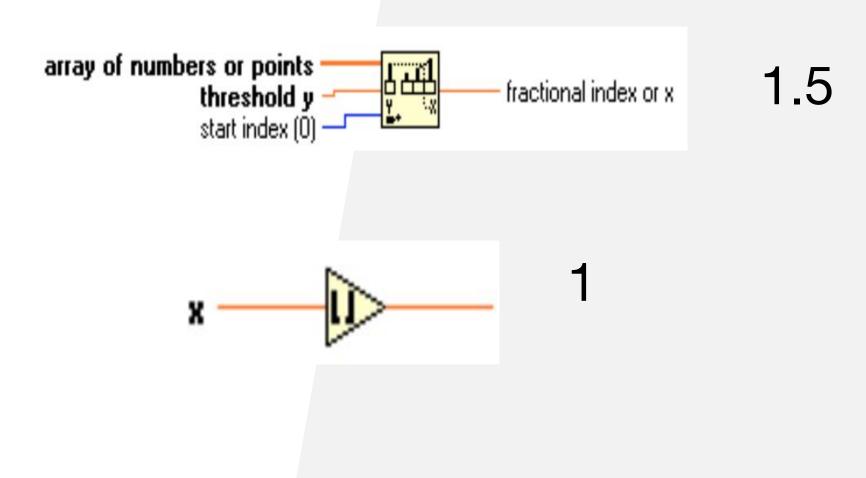




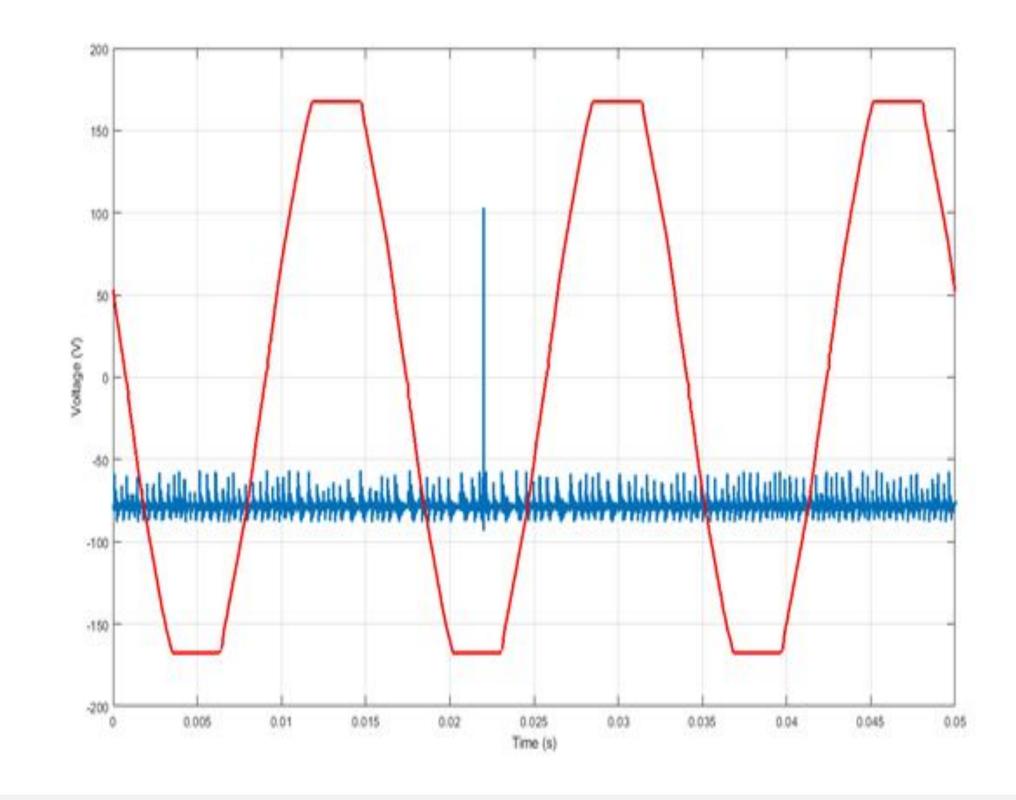


Load Angle

Zero crossing of sine signal = [1s 3s 6s] Time of pulse signal = [4.5s]

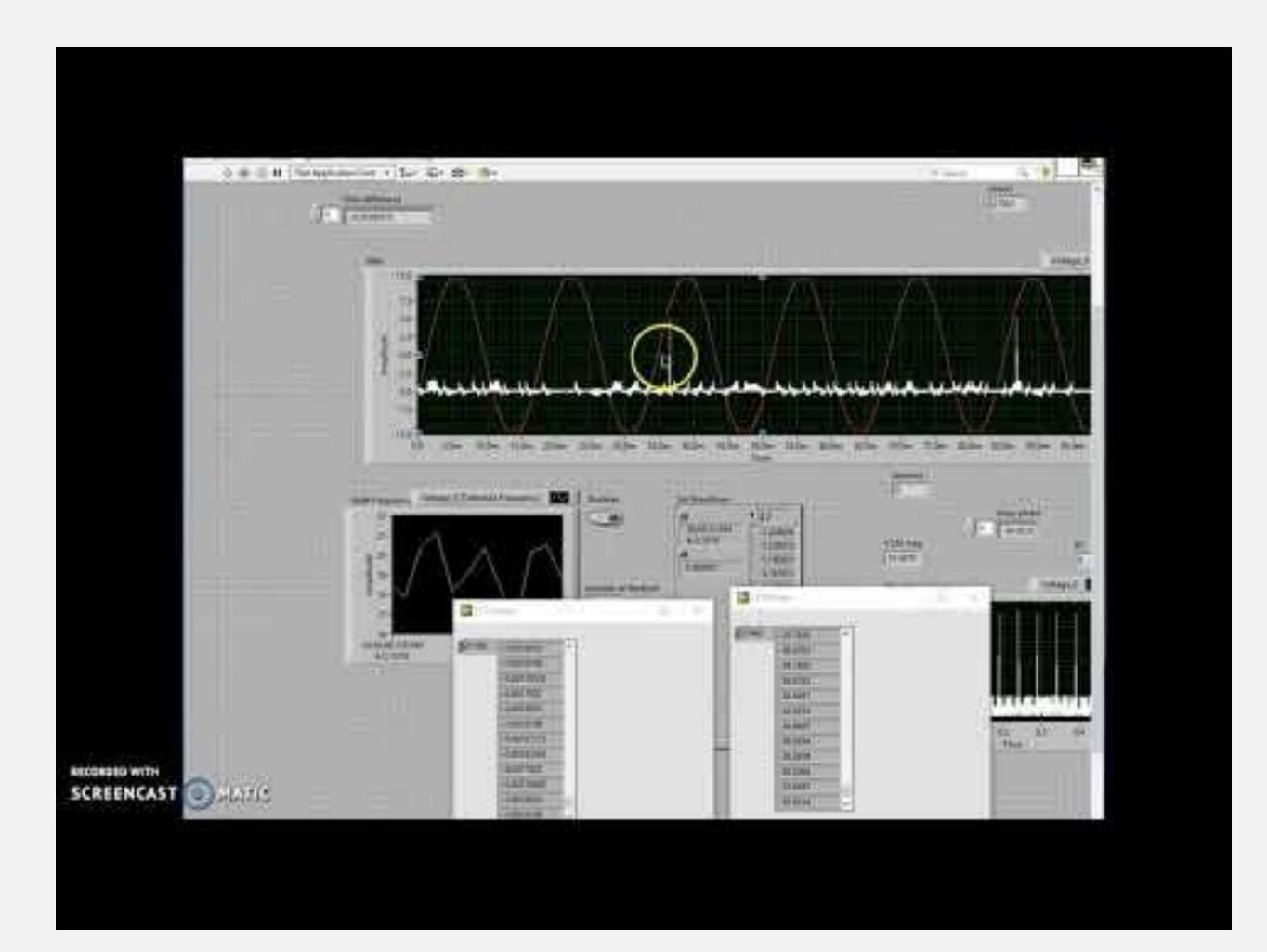








Load Angle Measurement





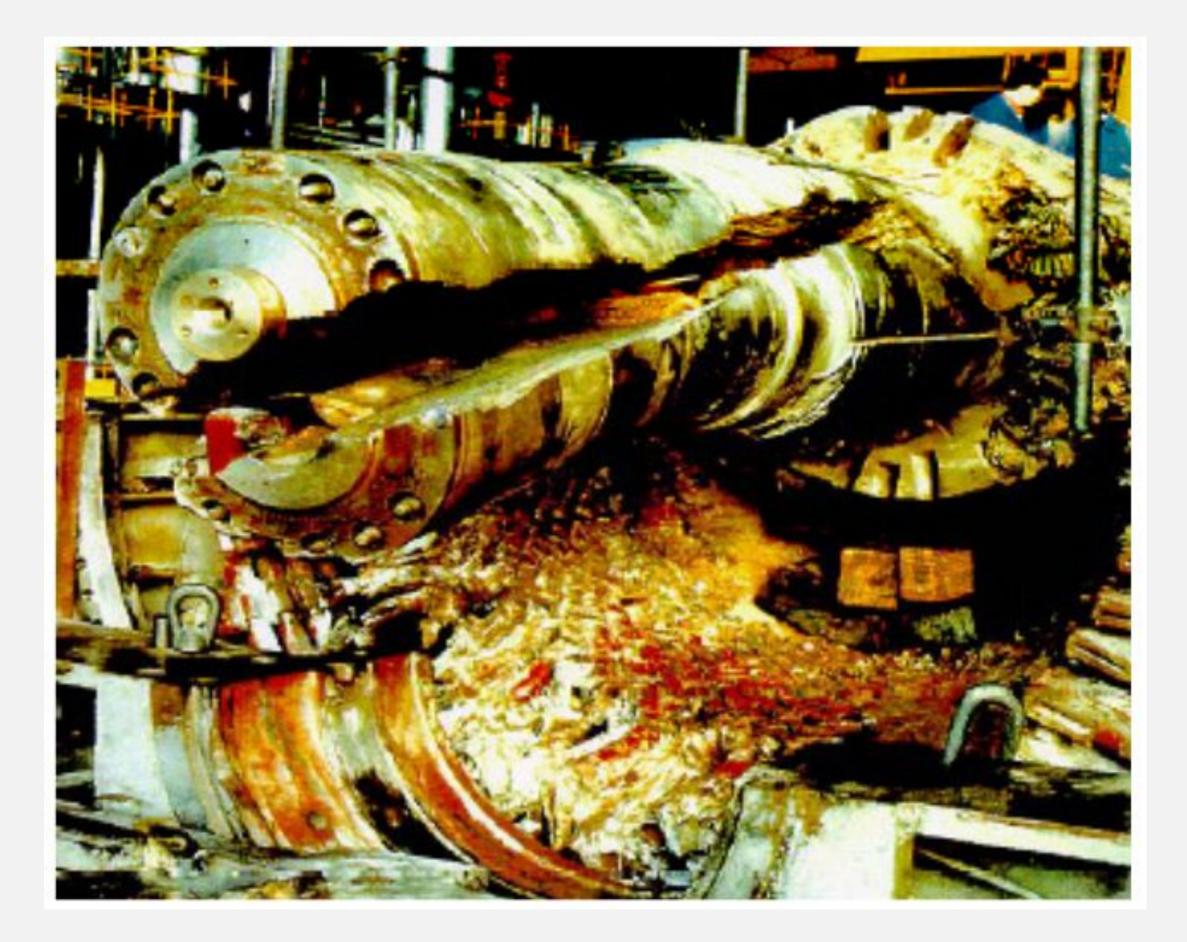


Budget

Project:SEL- Data	Acquisitio	n System f	or Synchron	nous Gener	rator Tran	sient Perfor	mance		
Last Updated	4/25/	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1							
				2018-2	019				Item
Expense Items	Sept	Oct	Nov	Dec	Jan	Feb	Mar	Apr	Total
Equipment/Tools:									
Devices:									
terminal board 2706						\$ 572.4			\$ 572
Vishay Dale Resister						\$ 4.39			\$ 4.39
Vishay Dale Resister						\$ 10.19			\$ 10.19
potential transformer						\$ 39.8			\$ 39.8
Torque cable					2 2	\$ 180			\$ 180
Shipping fee						\$ 25			\$ 25.04
potential transformer							12	\$ 66.9	\$ 66.9
Poster						-		\$ 82.5	\$ 82.5
								Totals	\$ 981.25

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Thank you Any Questions?

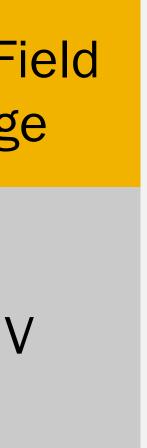


Appendix AC Generator Rating Plate

Rating Power	Rating Voltage	Rating Current	Power Factor	Rating Speed	Rating Field current	Rating Fi Voltage
13.5 kVA	220 V	35.4 A	0.9	50 HZ 1200 RPM	8 A	110 V







Appendix DC Motor Rating Plate

Rating Power	Rating
15-18 HP	11



VoltageRating Current.5 V113-140 A



Settling Time for Multichannel Measurements

Amount of time required for ADC connection to perform multichannel acquisition

Example: When acquiring data on the NI PXIe-6363 in a +-10V range, the multiplexer must remain on a single channel for up to 1.5 µs for the programmable gain instrumentation amplifier (NI-PGIA) to settle within 1 least significant bit (LSB) of the actual value with a full scale step input provided





Time Accuracy and Settling Time

PXI 6289		PXI 6251	
Timing Resolution	Timing Accuracy	Timing Resolution	Timing Accuracy
50 ns	50 ppm of sample rate	50 ns	50 ppm of sample rate

Settling Time for Multichannel Measurements 2 µs

Source : Specifications Explained: NI Multifunction I/O (MIO) DAQ

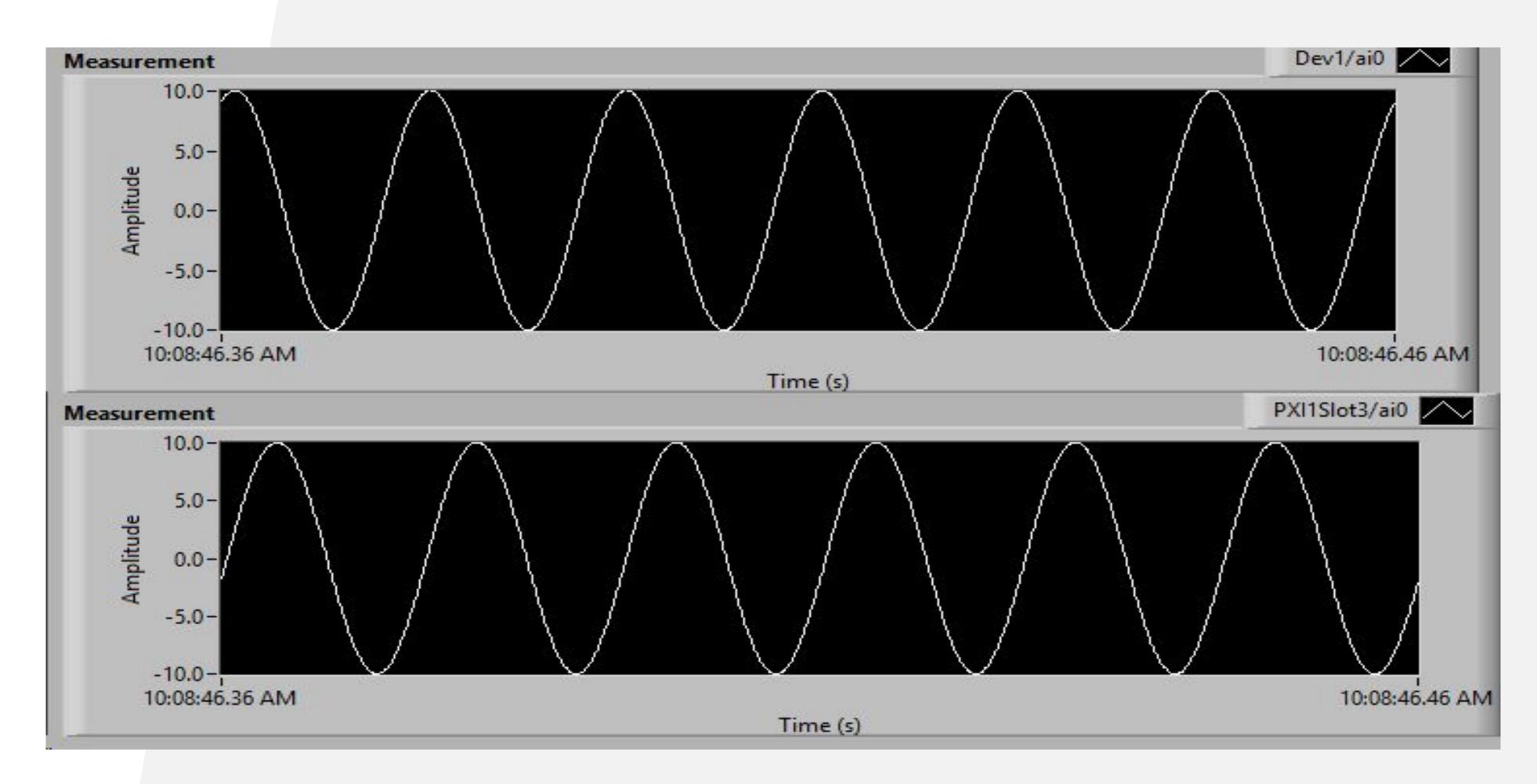
PXI 6251, PXI 6289 specification



Settling Time for Multichannel Measurements 1us to 1.5 µs



Synchronizing 2 DAQs









Synchronizing 2 DAQs

