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///IR Temperature read for multiple sensors
//Jacob Miller 12/7/2017
//updated for different number of sensors 18 April 2018

#include "IRTTemp.h"           //includes previously established code for irtemp

int sensorpins[6][3] = {          //setting up a matrix for pins
    {2, 3, 4},                  //sensor 1's pins
    {5, 6, 7},                  //sensor 2
    {8, 9, 10},                 //sensor 3
    {11, 12, 13}, //4
    {14, 15, 16}, //5
    {17, 18, 19}, //6
    //{20, 21, 22}, //7
    //{23, 24, 25}, //8
    //{26, 27, 28}, //9
    //{29, 30, 31}, //10
    //{32, 33, 34}, //11
    //{35, 36, 37} //12
};

int i;                           //Sensor number

byte PIN_ACQUIRE;               //starting Acquire, clock and data pins
byte PIN_CLOCK ;
byte PIN_DATA ;

String Message;

static const TempUnit SCALE=FAHRENHEIT;      //can change to CELCIUS

int wait;

void setup(void) {
    Serial.begin(9600);
}

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}

void loop(void) {
    Message = "";
    for(i=0;i<6;i++){           //For loop set up for only 6 sensors for expo
        PIN_DATA = sensorpins[i][2];
        PIN_CLOCK = sensorpins[i][1];
        PIN_ACQUIRE = sensorpins[i][0];

        IRTemp irTemp(PIN_ACQUIRE, PIN_CLOCK, PIN_DATA);      //use these pins to retreive the information

        float irTemperature = irTemp.getIRTemperature(SCALE);
        if (!isnan(irTemperature)) {
            Message = Message + String(irTemperature) + ",";
            delay(200);           //!!!important delay for clock with Labview
            float ambientTemperature = irTemp.getAmbientTemperature(SCALE); //retrieve information from
            ambient
            Message = Message + String(ambientTemperature) + ",";
            delay(200);
        }
        else{
            Message = Message + ",";
        }
    }

    Serial.println(Message);           //output is a string of however many sensors are connected
    separated by commas. Labview sorts out commas.

    //if (Serial.available() > 0) {

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// read the incoming byte:  
// wait = Serial.readString().toInt();  
// }  
// else {  
//   wait = 1000;  
// }  
  
delay(1000);  
}
```