

University of Idaho

College of Engineering

ENGINEERING RELEASE REVIEW UI DEBALERS 2.0

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OVERVIEW PRESENTATION TOPICS

- **I** Project Objective
- **I** Value Proposition
- **I** Background
- **I** Key attributes
- Manufacturing plan
- Design Validation
- **I** Project Schedule
- I Budget
- I Risks













PROJECT OBJECTIVE

- Improve current debaler prototype
- Make the prototype fully automated
- Add control system/algorithm to sense bale jamming and chute clogs
- I Test the final debaler prototype with different materials (Timothy hay, alfalfa, and straw) and find optimal running conditions







VALUE PROPOSITION THE PROBLEM

- Current debaling methods used in industry do not work well for automated processes
 - Produce too large of chunks of material
 - Produce too many fines (finely ground material)



Some Current Processes









VALUE PROPOSITION (CONTINUED) THE SOLUTION

- Our client needs an automated debaler for their assembly line process that produces a steady/consistent flow of debaled material and requires minimal operator input.
- By accomplishing the objective, the team will be able to:
 - Present client with working prototype along with in depth analysis of systems strengths and where it can improve
 - Present optimal running conditions for the tested materials

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BACKGROUND

- There is a need to debale straw, corn stover, hemp stalks, and other baled herbaceous crops for feeding into industrial processing equipment.
- The Fundamental Question: How can we effectively and efficiently turn baled material back into the loose material and feed it onto a conveyor for subsequent milling and processing?
- Forest Concepts needs a debaling mechanism to break down large square bales of stover, switchgrass, and similar materials into uniform streams that can be conveyed into their Crumbler® rotary shear comminution systems.





INITIAL DEBALER PROTOTYPE



PRODUCT REQUIREMENTS OUR PROTOTYPE REQUIREMENTS

- Convert 40lb 140lb bales into loose material
- Make system require minimal operator input
- Infeed Conveyor shall safely uphold a static force of 300lbs
- Sense bale jams
- System will operate on 120V
- System will break down into two main parts (processing head and infeed conveyor)
- System shall not exceed a total weight of 1000lbs
- The system shall have a maximum volume of 220 ft^3 (8ft X 5ft X 5.5ft)
- Transportable by common over the highway equipment

KEY ATTRIBUTES

Processing Head

Infeed Conveyor

Control Algorithm

IMPROVEMENTS TO PROCESSING HEAD

- Processing Head Shroud
 - Sheet metal enclosure
 - Integral chute

FLAKE HOLDING MECHANISM

- Adjustable bar
 - Accommodate different sized bales
- Flexible holder
 - Broom head, metal fingers, rubber mat

INFEED CONVEYOR

Id Hay elevator

- Powered by Motor w/ VFD
- Controlled by PLC
- I Manufacturing left
 - Add Gap adjustment Plate
 - Add chain cover for motor

Gap plate will be placed here

CONTROL SYSTEM DESIGN RECOMMENDATIONS

- **Components of System:**
 - Controller: PLC
 - Outputs: VFD Overload (Y or N)
 - Input: voltage sent to motor
 through VFD (Variable Frequency
 Drive)
 - This will set the initial motor speed

DESIGN VALIDATION

Requirement	Test	Test Subject	Target Date
Maximum weight of system shall not exceed the target weight of 1000lbs (4448.2 Newtons).	Weigh the conveyor and processing head (the two parts of the system) on the scale in JML.	Fully functional prototype	11/13/20
Maximum Volume of the Final prototype shall not exceed 220 ft^3 (8ft X 5ft X 5.5ft).	Use a tape measure to calculate the maximum length, width, and height dimensions of the prototype.	Fully functional prototype	11/20/21
The Infeed Conveyor shall be able to uphold a static force of 300 lbs.	Place 300 lbs on the Infeed Conveyor and make sure the system can hold the static load.	Fully functional Infeed Conveyor	11/20/21
Conveyor shall move two 140 lb bales to the processing head during operation, as well as two 40 lb bales.	Place two 140 lb bales on the conveyor and run the system. Make sure the bales are transformed into loose material without operator intervention.	Fully functional prototype	11/20/21
Test the control algorithm during operation.	Make sure that when a bale jam or chute clog occurs the system responds the way it is designed to. This may require manual bale jamming/chute clogging created by operator.	Fully functional prototype	3/20/21
Control input locations on the prototype shall be approximately 3 ft away from the processing head.	Use a tape measure to find the distance between the control panel and the processing head.	Fully functional prototype	3/19/21
The final prototype shall process the following materials: alfalfa, straw, and timothy hay.	Obtain the listed materials and run them through the system. During testing, record optimal motor speeds for some desired flow rates.	Fully functional prototype	3/19/21
The final prototype shall have a self-containing shroud to capture all loose material and funnel it into outfeed chute.	Process a few bales and ensure that the tines are free of loose material after operation.	Fully functional prototype	3/26/21
The final prototype shall collect all processed material and send it through the outfeed chute.	Process a few bales and ensure that all loose material falls through the chute.	Fully functional prototype	3/29/21-4/30/21

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