Excitation Control for a Synchronous Generator

Group:

Three Phase

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The goal of this project is to equip a generator used in the BEL Power Lab with a static exciter. The exciter should support a continuous operating mode and a three to four second burst.

The objective of this project is to make a more industrially realistic system for use with fault simulations. In addition the exciter will enhance the quality upper division labs that may use this system.



Semester Goals

Problem:

Design and implement a solid state exciter and related controls for a 15 kVA, 220V, 1200 RPM synchronous machine in UI Model Power System lab. The exciter should be capable of supporting fast field forcing to temporarily increase ac output voltage for voltage sags during simulated faults. The exciter should be capable of driving 24 A_{dc} at 300 V_{dc} for 3-4 seconds as well providing closed



Install, program, and test the exciter. Write a user guide on the operation and features of the exciter. Write a report on what the exciter is used for, how it works, and what it adds to the system.

ABB Unitrol 1020



Unitrol 1020 Key Advantages:

- Upgrade Options
 Upgradable with a power system stabilizer and a PM40 module
- High short term overload current 40 Amps for 10 seconds With PM40 option: 80 Amps for 10 seconds.
- Wide operating temperature range -40°C to +70°C

- Superior Voltage Regulation
 ± 0.10% from rated
- High Continuous Output Current Up to 20 Adc With PM40 option: 40 Adc
- Wide Input Voltage Range 9-300 Vac

Disadvantages of the Competitors

Basler DECS-200

- 15 Adc maximum continuous output
- ± 0.25% voltage regulation
- 56-277 Vac input range
- -40°C to +60°C
- No Ethernet ports

Basler DECS-250

- 15 Adc maximum continuous output
- ± 0.25% voltage regulation
- 56-277 Vac input range
- -40°C to +60°C

Product Comparison

Features	ABB Unitrol -1020 Basic	Basler DECS-200	Basler DECS-250
Exciter Output	Up to 20 Adc	< 15 Adc < 125 Vdc	< 15 Adc < 125 Vdc
Exciter Input	9-300 Vac	56-277 Vac	56-277 Vac
VR accuracy	±0.10%	±0.25%	±0.25%
Size	6.69" x 11.89" x 6.69"	8.08" x 7.32" x 12"	8.08" x 8.62" x 12"
Short Term Overload	< 40 Adc 10 seconds	< 300 Vdc < 30 Adc 10 seconds	< 300 Vdc < 30 Adc 10 seconds
Commissioning software	CMT1000 PC Software	BESTCOMSPlus PC Software	BESTCOMSPlus PC Software
Interface	USB, Ethernet, RS485, CAN bus, Front Panel HMI.	RS232, RS485 Modbus, Front Panel HMI.	USB, Ethernet, RS232, RS485 w/ options, J1939 CAN bus, IRIG-B, Front Panel HMI.
Optional Interface	Not Specified	DB9 for External Tracking	Profibus, RS232 and DB9 (ExternalTracking)
Maximum Burden	Not specified	3,070 VA	3,070 VA
Operating Temperature	-40 to 70 °C	-40 to 60 °C	-40 to 60 °C
Cost	Between \$5,000 and \$6,000	Between \$5,000 and \$6,000	Between \$4,000 and \$5,000

$$f_{se} = \frac{n_m P}{120} \tag{3-34}$$

where f_{se} = electrical frequency, in Hz

- n_m = mechanical speed of magnetic field, in r/min (equals speed of rotor for synchronous machines)
- P = number of poles

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$$P = s_P(f_{nl} - f_{sys})$$

where P = power output of the generator $f_{pl} =$ no-load frequency of the generator

 $f_{sys} =$ operating frequency of system

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sp = slope of curve, in kW/Hz or MW/Hz

$$P_{\max} = \frac{3V_{\oplus}E_A}{X_S}$$

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and the corresponding maximum torque is

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$$\tau_{max} = \frac{3V_{\phi}E_A}{\omega_m X_S}$$

$$P_{\rm out} = \sqrt{3} V_L I_L \cos \theta$$







Capability curve for a real synchronous generator rated at 470 kVA. (Courtesy of Marathon Electric Company.)



FIGURE 4-10 The full equivalent circuit of a three-phase synchronous generator.



FIGURE 4-11 The generator equivalent circuit connected in (a) Y and (b) Δ .

Tentative Schedule

December

05 Snapshot II

10 Finish and Submit Cost

Comparison

10 Order Exciter

January

- 02 Connect Exciter
- 03 Commission Exciter

February

02 Begin Tests

March

- 02 Test for Requirements
- 11 Snapshot III

April

- 02 Test for Failure
- 17 Write Test Procedures

May

- 01 Write User Manual
- 02 Engineering Design Expo
- 10 Order Exciter

