### University of Idaho



### **CSC Pi-Innovo OpenECU**

TEAM MEMBERS: Alex Kiss, Colin Parke, Zac Avelar and Hayden Hulse CLIENT: UICSC – Daniel Cordon



## **Value Proposition**

- Replicate and expand existing ECU functionality
- Allow space for extra sensors and systems
- Allow more advanced control
- Physical wiring + Simulink

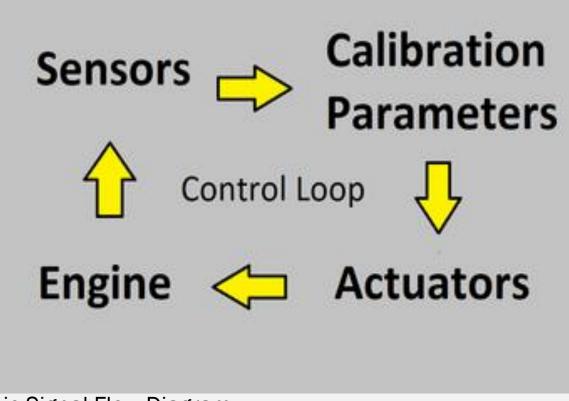






## Objective

- Develop connectivity between sensor inputs and control systems
- Evaluate engine control unit (ECU) functionality
- Develop useful documentation









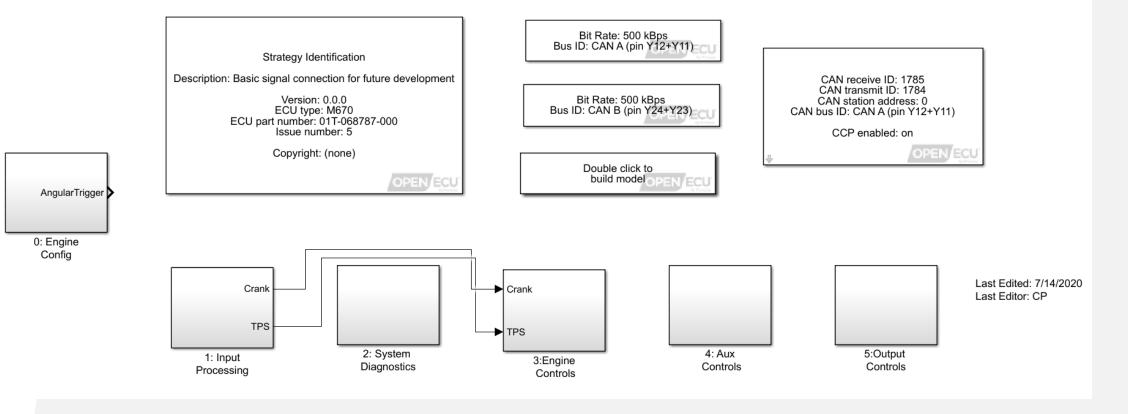
### **Product Requirements**

- Intuitive wiring with fully documented wiring diagram
- Parity with current ECU performance on dyno
- Framework for how to integrate future modifications/functions
- Streamlined documentation





### **DESIGN** MAIN LEVEL









### **DESIGN** CALCULATING OUTPUTS

### Speed Base Actuator Map Property Load Sensor Compensation Tables Sensor





# DESIGN

### LOOKUP TABLE EXAMPLE

Speed / Load	100	500	1000	2000	3000	4000	5000	6000	7000
0	61	65	70	80	90	100	110	120	130
15	<u>68.5</u>	72.5	77.5	87.5	97.5	107.5	117.5	127.5	137.5
30	76	80	85	95	105	115	125	135	145
45	83.5	87.5	92.5	102.5	112.5	122.5	132.5	142.5	152.5
60	91	95	100	110	120	130	140	150	160
75	98.5	102.5	107.5	117.5	127.5	137.5	147.5	157.5	167.5
90	106	110	115	125	135	145	155	165	175



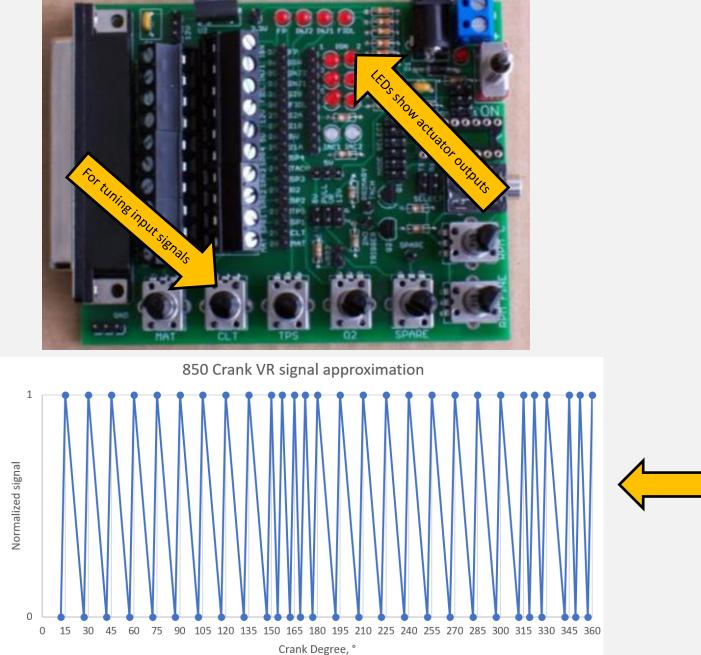
### Validation

- Input and output signals are connected and communicating to each other
- Input signal reads as expected
- Output signal reads as expected
- Signal processing properly converts input signal to usable output signal
- Input and output signals properly resolve to crank timing when applicable
- Run signal(s) in virtual engine/JimStim to ensure functionality under realistic conditions

Signal	Deadline
Throttle Position Sensor	7/17/2020
Injection	7/17/2020
Spark (Coil Pack)	7/17/2020
Crank pos	7/17/2020
RAVE act	7/24/2020
RAVE pos	7/24/2020
MAPTS	7/24/2020
Lamda	7/24/2020
Knock	7/31/2020
EGT	7/31/2020
Coolant	7/31/2020
Oil	7/31/2020
Mag in	8/7/2020



### **JimStim**





Simulated

crank

signal

position



### Schedule

#### Project timeline

- Task completion tracking
- Integrated schedule and Gantt Chart

#### University of Idaho Capstone Summer 2020

0	iversity of Idano Capstone Sum											
			HYPEIT									
		Project Start Date:	6/15/2020 (Mond	lay)								
		Display Week:	1				Week 1	Week 2	Week 3	Week 4	Week 5	Week 6
							6 / 15 / 20	6 / 22 / 20	6 / 29 / 20	6 / 20	7 / 13 / 20	7 / 20 / 2
3.10	[Insert Rows above this one, then Hide or Delete this row]			Sat 1/00/00	0%	0						
4	Class Due Dates	Team										
4.1	Team Contract	All	Mon 6/15/20	Mon 6/22/20	100%	6						
4.2	Client Interview Plan	All	Mon 6/15/20	Mon 6/22/20	100%	6						
4.3	Initiate Contact with Client	Colin Parke	Mon 6/15/20	Mon 6/22/20	100%	6						
4.4	DRAFT Budget Estimates	All	Mon 6/15/20	Mon 6/22/20	100%	6						
4.5	Client Visit and Interview	All	Mon 6/15/20	Thu 6/25/20	100%	9						
4.6	Product Requirements	All	Mon 6/15/20	Thu 6/25/20	100%	9						
4.7	Project Schedule	Hayden Hulse	Mon 6/15/20	Thu 7/02/20	45%	14						
4.8	Design Validation Plan	All	Mon 6/15/20	Fri 7/10/20	100%	20						
4.9	Portfolio, Wiki, & Logbooks (w/ review form)	All + Individual	Mon 6/15/20	Fri 7/10/20	100%	20						
4.10	Design Review	All	Mon 6/15/20	Mon 7/20/20	0%	26						
4.11	Value Proposition	All	Mon 6/15/20	Mon 7/20/20	100%	26						
4.12	Snapshot Storyboard	All	Mon 6/15/20	Thu 8/06/20	0%	39						
4.13	Technical Presentation	All	Mon 6/15/20	Thu 8/06/20	0%	39						
4.14	Portfolio, Wiki, Team Member Citizenship, & Logbook (w/ re- form)	view All + Individual	Mon 6/15/20	Fri 8/07/20	0%	40						
4.15	Final Hardware & Software, Design Report, Work Area Checkout, Electronic File Archive	All	Mon 6/15/20	Fri 8/07/20	0%	40						





## Budget

<b>Capstone Project Bud</b>	lget													
Project: HYPEIT														
Last Updated	7/16	/2020												
							2020					Item		
Expense Items	Ju	ine		luly	A	ug	Sept	Oct	Nov	Dec		Total		
Supplies / Parts / Services:														
M670 ECU	\$	2,000									\$	2,000		
Pi-Innovo Licenses	\$	1,000									\$	1,000		
MatLab Licenses	\$	1,000									\$	1,000		
SXL/GXL Wire	\$	144									\$	144		
Power Supply			\$	50							\$	50		
Dyno Computer					\$ 1	,000,					\$	1,000		
Cloth electrical tape					\$	18					\$	18		
											\$	-		
											\$	-		Expenses
													\$ 5,212	Subtotal
ME Shop Usage (est. Hrs):												Hours		
												0		
												0		
												0		
												0		
												0		
												0		
					Gra	aduat			-	A projects)		-	including	fringe (2.1%)
			Shop Overhead (only for SEA projects)											
			University Overhead (only for SEA projects)						\$	261.90	5% of all e	expenses		
										Totals	\$	5,212	\$ 5,500	\$ 288
													Budget	Excess





### **Documentation Plan**

- Complete Information Packet from 404
- Relocate all necessary files to team folder

1	Intr	roduction	
	1.1	Goals	
2	Req	quired Software	
	2.1	MATLAB	
	2.2	Simulink	
	2.3	Pi-Innovo	
3	Intr	roduction to MATLAB	
1	Intr	roduction to Simulink	
5	Intr	roduction to IC Engines/ECUs	
5	Intr	roduction to JimStim	
	6.1	JimStim Wheel Pattern	
7	Risk	k Reduction	
	7.1	Electrical Safety	
	7.2	Workspace Cleanliness	
	7.3	Version Control	
3	File	Management	
e	Арр	pendices	••••••
	9.1	Summer 2020 Capstone Design	
	9.1.	.1 Budget	
	9.1.	.2 Schedule	
	9.1.	.3 Team Contract	••••••
	9.1.	.4 Product Requirements	••••••
	9.1.	.5 Design Validation	•••••••
	9.1.	.6 Wiki Page	•••••••••••••••••••••••••••••••••••••••
	9.1.	7 Literate Program	•••••••
	9.1.	.8 Meeting Minutes	
	9.2	Program Outline	
	9.3	Abreviations	





### **Risk Management**

- Diligent documentation and classroom style education
- Kaizen type documents to teach the correct way of doing things
  - Electrical safety
  - File management and version control
- Calibratable and not-calibratable tables
- Hardware and software redundancy checks







# **QUESTIONS?**





